

## FEATURES

- High-Performance Static CMOS Technology
  - TMS470R1x 16/32-Bit RISC Core (ARM7TDMI™)
    - 28-MHz System Clock (48-MHz Pipeline Mode)
    - Independent 16/32-Bit Instruction Set
    - Open Architecture With Third-Party Support
    - Built-In Debug Module
    - Big-Endian Format Utilized
  - Integrated Memory
    - 128K-Byte Program Flash
      - One Bank With Ten Contiguous Sectors
      - Internal State Machine for Programming and Erase
    - 8K-Byte Static RAM (SRAM)
  - Operating Features
    - Core Supply Voltage ( $V_{CC}$ ): 1.81 V–2.05 V
    - I/O Supply Voltage ( $V_{CCIO}$ ): 3.0 V–3.6 V
    - Low-Power Modes: STANDBY and HALT
    - Extended Industrial Temperature Ranges
  - 470+ System Module
    - 32-Bit Address Space Decoding
    - Bus Supervision for Memory and Peripherals
    - Analog Watchdog (AWD) Timer
    - Real-Time Interrupt (RTI)
    - System Integrity and Failure Detection
  - Zero-Pin Phase-Locked Loop (ZPLL)-Based Clock Module With Prescaler
    - Multiply-by-4 or -8 Internal ZPLL Option
    - ZPLL Bypass Mode
  - Six Communication Interfaces:
    - Two Serial Peripheral Interfaces (SPIs)
      - 255 Programmable Baud Rates
    - Two Serial Communications Interfaces (SCIs)
      - 2<sup>24</sup> Selectable Baud Rates
      - Asynchronous/Isosynchronous Modes
  - Standard CAN Controller (SCC)
    - 16-Mailbox Capacity
    - Fully Compliant with CAN Protocol, Version 2.0B
  - Class II Serial Interface (C2Sla)
    - Two Selectable Data Rates
    - Normal Mode 10.4 Kbps and 4X Mode 41.6 Kbps
  - High-End Timer (HET)
    - 16 Programmable I/O Channels:
      - 14 High-Resolution Pins
      - 2 Standard-Resolution Pins
    - High-Resolution Share Feature (XOR)
    - HET RAM (64-Instruction Capacity)
  - 10-Bit Multi-Buffered ADC (MibADC) 16-Channel
    - 64-Word FIFO Buffer
    - Single- or Continuous-Conversion Modes
    - 1.55  $\mu$ s Minimum Sample and Conversion Time
    - Calibration Mode and Self-Test Features
  - 8 External Interrupts
  - Flexible Interrupt Handling
  - 11 Dedicated GIO Pins, 1 Input-Only GIO Pin, and 38 Additional Peripheral I/Os
  - External Clock Prescale (ECP) Module
    - Programmable Low-Frequency External Clock (CLK)
  - On-Chip Scan-Base Emulation Logic, IEEE Standard 1149.1 <sup>(1)</sup> (JTAG) Boundary-Scan Logic
  - 100-Pin Plastic Low-Profile Quad Flatpack (PZ Suffix)
- (1) The test-access port is compatible with the IEEE Standard 1149.1-1990, IEEE Standard Test-Access Port and Boundary Scan Architecture. Boundary scan is not supported on this device.



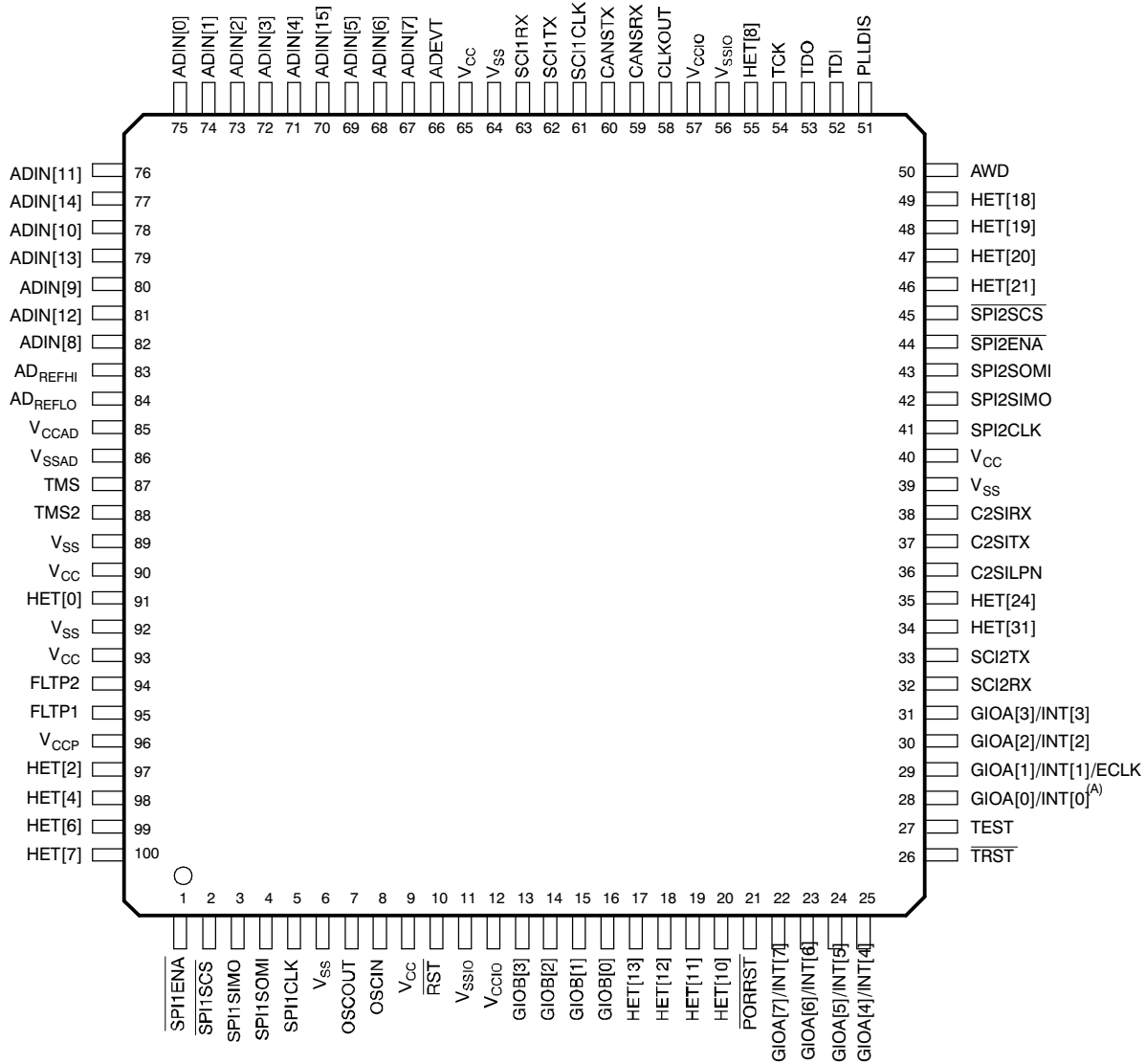
Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

ARM7TDMI is a trademark of Advanced RISC Machines (ARM) Limited.  
All trademarks are the property of their respective owners.

# TMS470R1A128 16/32-Bit RISC Flash Microcontroller

SPNS098A—JULY 2005—REVISED SEPTEMBER 2005

TMS470R1A128 100-Pin PZ Package (Top View)



A. GIOA[0]/INT0 (pin 28) is an input-only GIO pin.

## DESCRIPTION

The TMS470R1A128<sup>(1)</sup> devices are members of the Texas Instruments (TI) TMS470R1x family of general-purpose 16/32-bit reduced instruction set computer (RISC) microcontrollers. The TMS470R1x microcontroller offers high performance utilizing the high-speed ARM7TDMI 16/32-bit RISC central processing unit (CPU), resulting in a high instruction throughput while maintaining greater code efficiency. The ARM7TDMI 16/32-bit RISC CPU views memory as a linear collection of bytes numbered upwards from zero. The A128 utilizes the big-endian format, where the most significant byte of a word is stored at the lowest numbered byte and the least significant byte at the highest numbered byte.

High-end embedded control applications demand more performance from their controllers while maintaining low costs. The A128 RISC core architecture offers solutions to these performance and cost demands while maintaining low power consumption.

The A128 devices contain the following:

- ARM7TDMI 16/32-Bit RISC CPU
- TMS470R1x system module (SYS) with 470+ enhancements
- 128K-byte flash
- 8K-byte SRAM
- Zero-pin phase-locked loop (ZPLL) clock module
- Analog watchdog (AWD) timer
- Real-time interrupt (RTI) module
- Two serial peripheral interface (SPI) modules
- Two serial communications interface (SCI) modules
- Standard CAN controller (SCC)
- Class II serial interface (C2S1a)
- 10-bit, 16-input channel multi-buffered analog-to-digital converter (MibADC)
- High-end timer (HET) controlling 16 I/Os
- External Clock Prescale (ECP)
- Up to 49 I/O pins and 1 input-only pin

The functions performed by the 470+ system module (SYS) include:

- Address decoding
- Memory protection
- Memory and peripherals bus supervision
- Reset and abort exception management
- Prioritization for all internal interrupt sources
- Device clock control
- Parallel signature analysis (PSA)

This data sheet includes device-specific information such as memory and peripheral select assignment, interrupt priority, and a device memory map. For a more detailed functional description of the SYS module, see the *TMS470R1x System Module Reference Guide* (literature number SPNU189).

The A128 memory includes general-purpose SRAM supporting single-cycle read/write accesses in byte, halfword, and word modes.

The flash memory on the A128 devices is a nonvolatile, electrically erasable and programmable memory implemented with a 32-bit-wide data bus interface. The flash operates with a system clock frequency of up to 28 MHz. In pipeline mode, the flash operates with a system clock frequency of up to 48 MHz. For more detailed information on the flash, see the *F05 flash* section of this data sheet and the *TMS470R1x F05 Flash Reference Guide* (literature number SPNU213).

(1) Throughout the remainder of this document, the TMS470R1A128 device name will be referred to as either the full device name, TMS470R1A128, or as A128.

The A128 devices have six communication interfaces: two SPIs, two SCIs, an SCC, and a C2S1a. The SPI provides a convenient method of serial interaction for high-speed communications between similar shift-register type devices. The SCI is a full-duplex, serial I/O interface intended for asynchronous communication between the CPU and other peripherals using the standard non-return-to-zero (NRZ) format. The SCC uses a serial, multimaster communication protocol that efficiently supports distributed real-time control with robust communication rates of up to 1 megabit per second (Mbps). The SCC is ideal for applications operating in noisy and harsh environments (e.g., automotive and industrial fields) that require reliable serial communication or multiplexed wiring. The C2S1a allows the A128 to transmit and receive messages on a class II network following an SAE J1850 standard.<sup>(2)</sup>

For more detailed functional information on the C2S1a peripheral, see the *TMS470R1x Class II Serial Interface (C2S1a) Reference Guide* (literature number SPNU218).

The HET is an advanced intelligent timer that provides sophisticated timing functions for real-time applications. The timer is software-controlled, using a reduced instruction set, with a specialized timer micromachine and an attached I/O port. The HET can be used for compare, capture, or general-purpose I/O. It is especially well suited for applications requiring multiple sensor information and drive actuators with complex and accurate time pulses. For more detailed functional information on the HET, see the *TMS470R1x High-End Timer (HET) Reference Guide* (literature number SPNU199).

The A128 HET peripheral contains the XOR-share feature. This feature allows two adjacent HET high-resolution channels to be XORed together, making it possible to output smaller pulses than a standard HET. For more detailed information on the HET XOR-share feature, see the *TMS470R1x High-End Timer (HET) Reference Guide* (literature number SPNU199).

The A128 devices have a 10-bit-resolution sample-and-hold MibADC. The MibADC channels can be converted individually or can be grouped by software for sequential conversion sequences. There are three separate groupings, two of which are triggerable by an external event. Each sequence can be converted once when triggered or configured for continuous conversion mode. For more detailed functional information on the MibADC, see the *TMS470R1x Multi-Buffered Analog-to-Digital Converter (MibADC) Reference Guide* (literature number SPNU206).

The zero-pin phase-locked loop (ZPLL) clock module contains a phase-locked loop, a clock-monitor circuit, a clock-enable circuit, and a prescaler (with prescale values of 1–8). The function of the ZPLL is to multiply the external frequency reference to a higher frequency for internal use. The ZPLL provides ACLK to the system (SYS) module. The SYS module subsequently provides system clock (SYSCLK), real-time interrupt clock (RTICLK), CPU clock (MCLK), and peripheral interface clock (ICLK) to all other A128 device modules. For more detailed functional information on the ZPLL, see the *TMS470R1x Zero-Pin Phase-Locked Loop (ZPLL) Clock Module Reference Guide* (literature number SPNU212).

**NOTE:**

ACLK should not be confused with the MibADC internal clock, ADCLK. ACLK is the continuous system clock from an external resonator/crystal reference.

The A128 devices also have an external clock prescaler (ECP) module that when enabled, outputs a continuous external clock (ECLK) on a specified GIO pin. The ECLK frequency is a user-programmable ratio of the peripheral interface clock (ICLK) frequency. For more detailed functional information on the ECP, see the *TMS470R1x External Clock Prescaler (ECP) Reference Guide* (literature number SPNU202).

(2) SAE Standard J1850 Class B Data Communication Network Interface

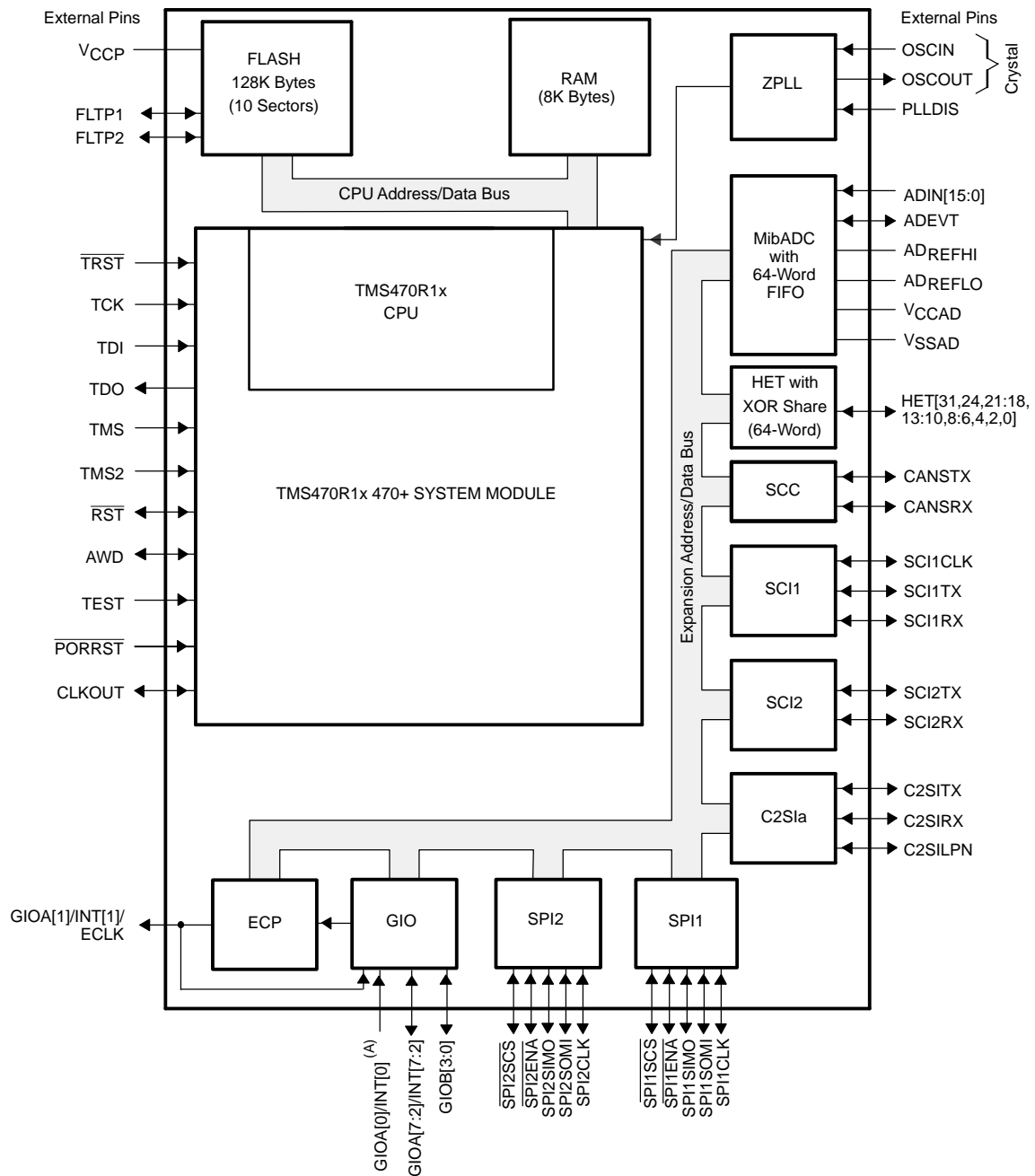
## Device Characteristics

The TMS470R1A128 devices are a derivative of the F05 system emulation device SE470R1VB8AD. [Table 1](#) identifies all the characteristics of the TMS470R1A128 devices except the SYSTEM and CPU, which are generic.

**Table 1. Device Characteristics**

CHARACTERISTICS	DEVICE DESCRIPTION	COMMENTS
<b>MEMORY</b>		
For the number of memory selects on this device, see the "Memory Selection Assignment" table, <a href="#">Table 3</a> .		
INTERNAL MEMORY	128K-Byte flash 8K-Byte SRAM	Flash is pipeline-capable. The A128 RAM is implemented in one 8K-byte array selected by two memory-select signals (see the "Memory Selection Assignment" table, <a href="#">Table 3</a> ).
<b>PERIPHERALS</b>		
For the device-specific interrupt priority configurations, see the Interrupt Priority table ( <a href="#">Table 6</a> ). For the 1K-byte peripheral address ranges and their peripheral selects, see the "A128 Peripherals, System Module, and Flash Base Addresses" table, <a href="#">Table 5</a> .		
CLOCK	ZPLL Zero-pin PLL has no external loop filter pins.	
GENERAL-PURPOSE I/Os	11 I/O 1 Input only	Port A has 8 external pins, and Port B has 4 external pins.
ECP	YES	
C2S1a	1	
SCI	1 (3-pin) 1 (2-pin)	SCI2 has no external clock pin, only transmit/receive pins (SCI2TX and SCI2RX).
CAN (HECC and/or SCC)	1 SCC	Standard CAN controller
SPI (5-pin, 4-pin or 3-pin)	2 (5-pin)	
HET with XOR Share	16 I/O	The A128 devices have both the logic and registers for a full 32-I/O HET implemented, even though not all 32 pins are available externally. The high-resolution (HR) SHARE feature allows even-numbered HR pins to share the next higher odd-numbered HR pin structures. This HR sharing is independent of whether or not the odd pin is available externally. If an odd pin is available externally and shared, then the odd pin can only be used as a general-purpose I/O. For more information on HR SHARE, see the <i>TMS470R1x High-End Timer (HET) Reference Guide</i> (literature number SPNU199).
HET RAM	64-Instruction Capacity	
MibADC	10-bit, 16-channel 64-word FIFO	Both the logic and registers for a full 16-channel MibADC are present.
CORE VOLTAGE	1.81–2.06 V	When used from -40°C to 85°C, the core voltage range for A128 devices is 1.70–2.06 V.
I/O VOLTAGE	3.0–3.6 V	
PINS	100	
PACKAGE	PZ	

**Functional Block Diagram**



A. GIOA[0]/INT[0] is an input-only GIO pin.

**Table 2. Terminal Functions**

TERMINAL		TYPE <sup>(1)(2)</sup>	INTERNAL PULLUP/ PULLDOWN <sup>(3)</sup>	DESCRIPTION
NAME	PIN NUMBER			
<b>HIGH-END TIMER (HET)</b>				
HET[0]	91	3.3-V I/O	IPD (20 $\mu$ A)	<p>The A128 devices have both the logic and registers for a full 32-I/O HET implemented, even though not all 32 pins are available externally.</p> <p>Timer input capture or output compare. The HET[31:0] applicable pins can be programmed as general-purpose input/output (GIO) pins.</p> <p>HET[21:18, 13:10, 8, 7, 6, 4, 2, 0] are high-resolution pins and HET[31, 24] are standard-resolution pins for A128.</p> <p>The high-resolution (HR) SHARE feature allows even HR pins to share the next higher odd HR pin structures. This HR sharing is independent of whether or not the odd pin is available externally. If an odd pin is available externally and shared, then the odd pin can only be used as a general-purpose I/O.</p> <p>For more information on HR SHARE, see the <i>TMS470R1x High-End Timer Reference Guide</i> (literature number SPNU199).</p>
HET[2]	97			
HET[4]	98			
HET[6]	99			
HET[7]	100			
HET[8]	55			
HET[10]	20			
HET[11]	19			
HET[12]	18			
HET[13]	17			
HET[18]	49			
HET[19]	48			
HET[20]	47			
HET[21]	46			
HET[24]	35			
HET[31]	34			
<b>STANDARD CAN CONTROLLER (SCC)</b>				
CANSRX	59	3.3-V I/O		SCC receive pin or GIO pin
CANSTX	60	3.3-V I/O	IPU (20 $\mu$ A)	SCC transmit pin or GIO pin
<b>CLASS II SERIAL INTERFACE (C2Sla)</b>				
C2SILPN	36	3.3-V I/O	IPD (20 $\mu$ A)	C2Sla module loopback enable pin or GIO pin
C2SIRX	38	3.3-V I/O		C2Sla module receive data input pin or GIO pin
C2SITX	37	3.3-V I/O	IPD (20 $\mu$ A)	C2Sla module transmit data input pin or GIO pin

- (1) I = input, O = output, PWR = power, GND = ground, REF = reference voltage, NC = no connect
- (2) All I/O pins, except RST, are configured as inputs while  $\overline{\text{PORRST}}$  is low and immediately after  $\overline{\text{PORRST}}$  goes high.
- (3) IPD = internal pulldown, IPU = internal pullup (all internal pullups and pulldowns are active on input pins, independent of the  $\overline{\text{PORRST}}$  state.)

**Table 2. Terminal Functions (continued)**

TERMINAL		TYPE <sup>(1)(2)</sup>	INTERNAL PULLUP/PULLDOWN <sup>(3)</sup>	DESCRIPTION		
NAME	PIN NUMBER					
<b>GENERAL-PURPOSE I/O (GIO)</b>						
GIOA[0]/INT0	28	3.3-V I	IPD (20 $\mu$ A)	General-purpose input/output pins. GIOA[0]/INT[0] is an input-only pin. GIOA[7:0]/INT[7:0] are interrupt-capable pins. GIOA[1]/INT[1]/ECLK pin is multiplexed with the external clock-out function of the external clock prescale (ECP) module.		
GIOA[1]/INT1/ECLK	29	3.3-V I/O				
GIOA[2]/INT2	30					
GIOA[3]/INT3	31					
GIOA[4]/INT4	25					
GIOA[5]/INT5	24					
GIOA[6]/INT6	23					
GIOA[7]/INT7	22					
GIOB[0]	16					
GIOB[1]	15					
GIOB[2]	14					
GIOB[3]	13					
<b>MULTI-BUFFERED ANALOG-TO-DIGITAL CONVERTER (MibADC)</b>						
ADEVT	66	3.3-V I/O			IPD (20 $\mu$ A)	MibADC event input. ADEVT can be programmed as a GIO pin.
ADIN[0]	75	3.3-V I		16-channel MibADC. MibADC analog input pins		
ADIN[1]	74					
ADIN[2]	73					
ADIN[3]	72					
ADIN[4]	71					
ADIN[5]	69					
ADIN[6]	68					
ADIN[7]	67					
ADIN[8]	82					
ADIN[9]	80					
ADIN[10]	78					
ADIN[11]	76					
ADIN[12]	81					
ADIN[13]	79					
ADIN[14]	77					
ADIN[15]	70					
AD <sub>REFHI</sub>	83	3.3-V REF I		MibADC module high-voltage reference input		
AD <sub>REFLO</sub>	84	GND REF I		MibADC module low-voltage reference input		
V <sub>CCAD</sub>	85	3.3-V PWR		MibADC analog supply voltage		
V <sub>SSAD</sub>	86	GND		MibADC analog ground reference		

**Table 2. Terminal Functions (continued)**

TERMINAL		TYPE <sup>(1)(2)</sup>	INTERNAL PULLUP/PULLDOWN <sup>(3)</sup>	DESCRIPTION
NAME	PIN NUMBER			
<b>SERIAL PERIPHERAL INTERFACE 1 (SPI1)</b>				
SPI1CLK	5	3.3-V I/O	IPD (20 $\mu$ A)	SPI1 clock. SPI1CLK can be programmed as a GIO pin.
$\overline{\text{SPI1ENA}}$	1			SPI1 chip enable. $\overline{\text{SPI1ENA}}$ can be programmed as a GIO pin.
$\overline{\text{SPI1SCS}}$	2			SPI1 slave chip select. $\overline{\text{SPI1SCS}}$ can be programmed as a GIO pin.
SPI1SIMO	3			SPI1 data stream. Slave in/master out. SPI1SIMO can be programmed as a GIO pin.
SPI1SOMI	4			SPI1 data stream. Slave out/master in. SPI1SOMI can be programmed as a GIO pin.
<b>SERIAL PERIPHERAL INTERFACE 2 (SPI2)</b>				
SPI2CLK	41	3.3-V I/O	IPD (20 $\mu$ A)	SPI2 clock. SPI2CLK can be programmed as a GIO pin.
$\overline{\text{SPI2ENA}}$	44			SPI2 chip enable. $\overline{\text{SPI2ENA}}$ can be programmed as a GIO pin.
$\overline{\text{SPI2SCS}}$	45			SPI2 slave chip select. $\overline{\text{SPI2SCS}}$ can be programmed as a GIO pin.
SPI2SIMO	42			SPI2 data stream. Slave in/master out. SPI2SIMO can be programmed as a GIO pin.
SPI2SOMI	43			SPI2 data stream. Slave out/master in. SPI2SOMI can be programmed as a GIO pin.
<b>ZERO-PIN PHASE-LOCKED LOOP (ZPLL)</b>				
OSCIN	8	1.8-V I		Crystal connection pin or external clock input
OSCOU	7	1.8-V O		External crystal connection pin
PLLDIS	51	3.3-V I	IPD (20 $\mu$ A)	Enable/disable the ZPLL. The ZPLL can be bypassed and the oscillator becomes the system clock. If not in bypass mode, TI recommends that PLLDIS be connected to ground or pulled down to ground by an external resistor.
<b>SERIAL COMMUNICATIONS INTERFACE 1 (SCI1)</b>				
SCI1CLK	61	3.3-V I/O	IPD (20 $\mu$ A)	SCI1 clock. SCI1CLK can be programmed as a GIO pin.
SCI1RX	63	3.3-V I/O	IPU (20 $\mu$ A)	SCI1 data receive. SCI1RX can be programmed as a GIO pin.
SCI1TX	62	3.3-V I/O	IPU (20 $\mu$ A)	SCI1 data transmit. SCI1TX can be programmed as a GIO pin.
<b>SERIAL COMMUNICATIONS INTERFACE 2 (SCI2)</b>				
SCI2RX	32	3.3-V I/O	IPU (20 $\mu$ A)	SCI2 data receive. SCI2RX can be programmed as a GIO pin.
SCI2TX	33	3.3-V I/O	IPU (20 $\mu$ A)	SCI2 data transmit. SCI2TX can be programmed as a GIO pin.
<b>SYSTEM MODULE (SYS)</b>				
CLKOUT	58	3.3-V I/O	IPD (20 $\mu$ A)	Bidirectional pin. CLKOUT can be programmed as a GIO pin or the output of SYSCLK, ICLK, or MCLK.
$\overline{\text{PORRST}}$	21	3.3-V I	IPD (20 $\mu$ A)	Input master chip power-up reset. External $V_{CC}$ monitor circuitry must assert a power-on reset.
$\overline{\text{RST}}$	10	3.3-V I/O	IPU (20 $\mu$ A)	<p>Bidirectional reset. The internal circuitry can assert a reset, and an external system reset can assert a device reset.</p> <p>On <math>\overline{\text{RST}}</math>, the output buffer is implemented as an open drain (drives low only).</p> <p>To ensure an external reset is not arbitrarily generated, TI recommends that an external pullup resistor be connected to <math>\overline{\text{RST}}</math>.</p>
<b>WATCHDOG/REAL-TIME INTERRUPT (WD/RTI)</b>				
AWD	50	3.3-V I/O	IPD (20 $\mu$ A)	<p>Analog watchdog reset. The AWD pin provides a system reset if the WD KEY is not written in time by the system, providing an external RC network circuit is connected. If the user is not using AWD, TI recommends that AWD be connected to ground or pulled down to ground by an external resistor.</p> <p>For more details on the external RC network circuit, see the <i>TMS470R1x System Module Reference Guide</i> (literature number SPNU189) and the application note <i>Analog Watchdog Resistor, Capacitor and Discharge Interval Selection Constraints</i> (literature number SPNA005).</p>

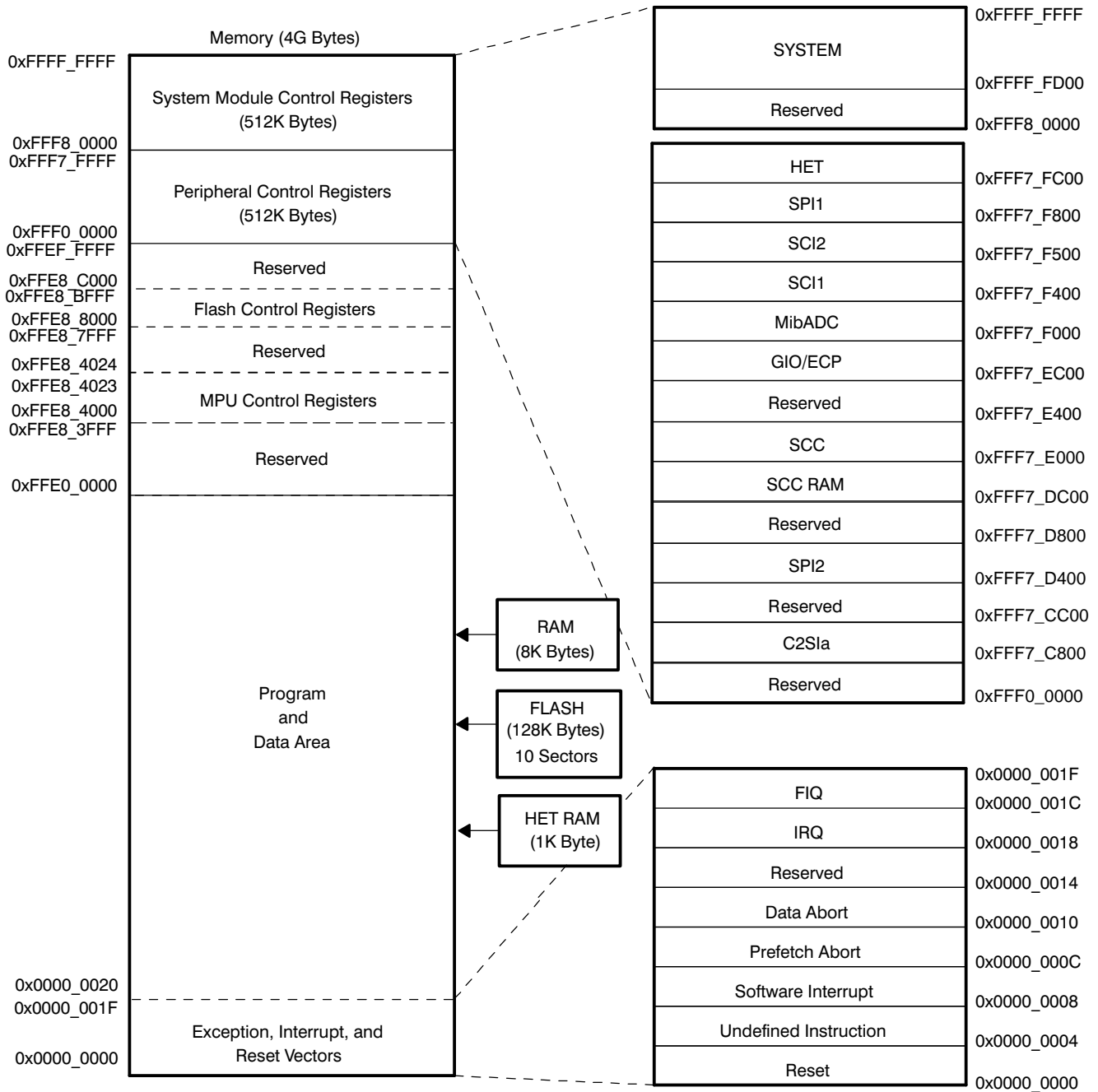
**Table 2. Terminal Functions (continued)**

TERMINAL		TYPE <sup>(1)(2)</sup>	INTERNAL PULLUP/ PULLDOWN <sup>(3)</sup>	DESCRIPTION
NAME	PIN NUMBER			
<b>TEST/DEBUG (T/D)</b>				
TCK	54	3.3-V I	IPD (20 $\mu$ A)	Test clock. TCK controls the test hardware (JTAG).
TDI	52	3.3-V I	IPU (20 $\mu$ A)	Test data in. TDI inputs serial data to the test instruction register, test data register, and programmable test address (JTAG).
TDO	53	3.3-V O	IPD (20 $\mu$ A)	Test data out. TDO outputs serial data from the test instruction register, test data register, identification register, and programmable test address (JTAG).
TEST	27	3.3-V I	IPD (20 $\mu$ A)	Test enable. Reserved for internal use only. TI recommends that TEST be connected to ground or pulled down to ground by an external resistor.
TMS	87	3.3-V I	IPU (20 $\mu$ A)	Serial input for controlling the state of the CPU test access port (TAP) controller (JTAG).
TMS2	88	3.3-V I	IPU (20 $\mu$ A)	Serial input for controlling the second TAP. TI recommends that TMS2 be connected to V <sub>CCIO</sub> or be pulled up to V <sub>CCIO</sub> by an external resistor.
<del>TRST</del>	26	3.3-V I	IPD (20 $\mu$ A)	Test hardware reset to TAP1 and TAP2. IEEE Standard 1149-1 (JTAG) Boundary-Scan Logic. TI recommends that <del>TRST</del> be pulled down to ground by an external resistor.
<b>FLASH</b>				
FLTP1	95	NC		Flash test pads 1 and 2. <b>For proper operation, these pins must not be connected (no connect [NC]).</b>
FLTP2	94			
V <sub>CCP</sub>	96	3.3-V PWR		Flash external pump voltage (3.3 V)
<b>SUPPLY VOLTAGE CORE (1.8 V)</b>				
V <sub>CC</sub>	9	1.8-V PWR		Core logic supply voltage
	40			
	65			
	90			
	93			
<b>SUPPLY VOLTAGE DIGITAL I/O (3.3 V)</b>				
V <sub>CCIO</sub>	12	3.3-V PWR		Digital I/O supply voltage
	57			
<b>SUPPLY GROUND CORE</b>				
V <sub>SS</sub>	6	GND		Core supply ground reference
	39			
	64			
	89			
	92			
<b>SUPPLY GROUND DIGITAL I/O</b>				
V <sub>SSIO</sub>	11	GND		Digital I/O supply ground reference
	56			

## A128 Device-Specific Information

### Memory

Figure 1 shows the memory map of the TMS470R1A128 device.



- A. Memory addresses are configurable by the system (SYS) module within the range of 0x0000\_0000 to 0xFFE0\_0000.
- B. The CPU registers are not part of the memory map.

**Figure 1. Memory Map**

## Memory Selects

Memory selects allow the user to address memory arrays (i.e., flash, RAM, and HET RAM) at user-defined addresses. Each memory select has its own set (low and high) of memory base address registers (MFBAHRx and MFBALRx) that together define the array's starting (base) address, block size, and protection.

The base address of each memory select is configurable to any memory address boundary that is a multiple of the decoded block size. For more information on how to control and configure these memory select registers, see the bus structure and memory sections of the *TMS470R1x System Module Reference Guide* (literature number SPNU189).

For the memory selection assignments and the memory selected, see [Table 3](#).

**Table 3. Memory Selection Assignment**

MEMORY SELECT	MEMORY SELECTED (ALL INTERNAL)	MEMORY SIZE	MPU	MEMORY BASE ADDRESS REGISTER	STATIC MEM CTL REGISTER
0 (fine)	FLASH	128K	NO	MFBAHR0 and MFBALR0	
1 (fine)	FLASH		NO	MFBAHR1 and MFBALR1	
2 (fine)	RAM	8K <sup>(1)</sup>	YES	MFBAHR2 and MFBALR2	
3 (fine)	RAM		YES	MFBAHR3 and MFBALR3	
4 (fine)	HET RAM	1K		MFBAHR4 and MFBALR4	SMCR1

(1) The starting addresses for both RAM memory-select signals *cannot* be offset from each other by a multiple of the user-defined block size in the memory-base address register.

## RAM

The A128 devices contain 8K bytes of internal static RAM configurable by the SYS module to be addressed within the range of 0x0000\_0000 to 0xFFE0\_0000. This RAM is implemented in one 8K-byte array selected by two memory-select signals. This configuration imposes an additional constraint on the memory map for RAM; the starting addresses for both RAM memory selects *cannot* be offset from each other by the multiples of the size of the physical RAM (i.e., 8K bytes for the A128 device). The RAM is addressed through memory selects 2 and 3.

The RAM can be protected by the memory protection unit (MPU) portion of the SYS module, allowing the user finer blocks of memory protection than is allowed by the memory selects. The MPU is ideal for protecting an operating system while allowing access to the current task. For more detailed information on the MPU portion of the SYS module and memory protection, see the memory section of the *TMS470R1x System Module Reference Guide* (literature number SPNU189).

## F05 flash

The F05 flash memory is a nonvolatile electrically erasable and programmable memory implemented with a 32-bit-wide data bus interface. The F05 flash has an external state machine for programming and erase functions. See the *flash read* and *flash program and erase* sections.

### NOTE:

Flash must be mapped to a boundary of zero or a multiple of 0x00100000. RAM cannot be mapped into the same 0x00100000 space.

## flash protection keys

The A128 devices provide flash protection keys. These four 32-bit protection keys prevent program/erase/compaction operations from occurring until after the four protection keys have been matched by the CPU loading the correct user keys into the FMPKEY control register. The protection keys on the A128 are located in the last four words of the first 8K sector. For more detailed information on the flash protection keys and the FMPKEY control register, see the protection keys portions of the *TMS470R1x F05 Flash Reference Guide* (literature number SPNU213).

**flash read**

The A128 Flash memory is configurable by the SYS module to be addressed within the range of 0x0000\_0000 to 0xFFE0\_0000. The flash is addressed through memory selects 0 and 1.

**NOTE:**

The flash external pump voltage ( $V_{CCP}$ ) is required for all operations (program, erase, and read).

**flash pipeline mode**

When in pipeline mode, the flash operates with a system clock frequency of up to 48 MHz (versus a system clock in normal mode of up to 28 MHz). Flash in pipeline mode is capable of accessing 64-bit words and provides two 32-bit pipelined words to the CPU. Also in pipeline mode, the flash can be read with no wait states when memory addresses are contiguous (after the initial 1-or 2-wait-state reads).

**NOTE:**

After a system reset, pipeline mode is **disabled** (the ENPIPE bit FMREGOPT[0] = 0). In other words, the A128 devices power up and come out of reset in non-pipeline mode. Furthermore, setting the flash configuration mode bit (GLBCTRL[4]) will override pipeline mode.

**flash program and erase**

The A128 device flash has one 128K-byte bank that consists of ten sectors. These ten sectors are shown in [Table 4](#).

**Table 4. Flash Sectors**

SECTOR NO.	SEGMENT	LOW ADDRESS	HIGH ADDRESS
0	8K Bytes	0x0000_0000	0x0000_1FFF
1	8K Bytes	0x0000_2000	0x0000_3FFF
2	16K Bytes	0x0000_4000	0x0000_7FFF
3	16K Bytes	0x0000_8000	0x0000_BFFF
4	16K Bytes	0x0000_C000	0x0000_FFFF
5	16K Bytes	0x0001_0000	0x0001_3FFF
6	16K Bytes	0x0001_4000	0x0001_7FFF
7	16K Bytes	0x0001_8000	0x0001_BFFF
8	8K Bytes	0x0001_C000	0x0001_DFFF
9	8K Bytes	0x0001_E000	0x0001_FFFF

The minimum size for an erase operation is one sector. The maximum size for a program operation is one 16-bit word.

**NOTE:**

The flash external pump voltage ( $V_{CCP}$ ) is required for all operations (program, erase, and read).

For more detailed information on flash program and erase operations, see the *TMS470R1x F05 Flash Reference Guide* (literature number SPNU213).

**HET RAM**

The A128 devices contain HET RAM. The HET RAM has a 64-instruction capability. The HET RAM is configurable by the SYS module to be addressed within the range of 0x0000\_0000 to 0xFFE0\_0000. The HET RAM is addressed through memory select 4.

**Peripheral Selects and Base Addresses**

The A128 devices use 10 of the 16 peripheral selects to decode the base addresses of the peripherals. These peripheral selects are fixed and transparent to the user since they are part of the decoding scheme used by the SYS module.

Control registers for the peripherals, SYS module, and flash begin at the base addresses shown in [Table 5](#).

**Table 5. TMS470R1A128 Peripherals, System Module, and Flash Base Addresses**

CONNECTING MODULE	ADDRESS RANGE		PERIPHERAL SELECTS
	BASE ADDRESS	ENDING ADDRESS	
SYSTEM	0xFFFF_FD00	0xFFFF_FFFF	N/A
Reserved	0xFFFF8_0000	0xFFFF_FCFF	N/A
HET	0xFFFF7_FC00	0xFFFF7_FFFF	PS[0]
SPI1	0xFFFF7_F800	0xFFFF7_FBFF	PS[1]
SCI2	0xFFFF7_F500	0xFFFF7_F7FF	PS[2]
SCI1	0xFFFF7_F400	0xFFFF7_F4FF	
ADC	0xFFFF7_F000	0xFFFF7_F3FF	PS[3]
GIO/ECP	0xFFFF7_EC00	0xFFFF7_EFFF	PS[4]
Reserved	0xFFFF7_E400	0xFFFF7_EBFF	PS[5]–PS[6]
SCC	0xFFFF7_E000	0xFFFF7_E3FF	PS[7]
SCC RAM	0xFFFF7_DC00	0xFFFF7_DFFF	PS[8]
Reserved	0xFFFF7_D800	0xFFFF7_DBFF	PS[9]
SPI2	0xFFFF7_D400	0xFFFF7_D7FF	PS[10]
Reserved	0xFFFF7_CC00	0xFFFF7_D3FF	PS[11]–PS[12]
C2SIA	0xFFFF7_C800	0xFFFF7_CBFF	PS[13]
Reserved	0xFFFF7_C000	0xFFFF7_C7FF	PS[14]–PS[15]
Reserved	0xFFFF0_0000	0xFFFF7_BFFF	N/A
Flash Control Registers	0xFFE8_8000	0xFFE8_BFFF	N/A
MPU Control Registers	0xFFE8_4000	0xFFE8_4023	N/A

## Interrupt Priority

The central interrupt manager (CIM) portion of the SYS module manages the interrupt requests from the device modules (i.e., SPI1 or SPI2, SCI1 or SCI2, and RTI, etc.).

Although the CIM can accept up to 32 interrupt request signals, the A128 devices only use 21 of those interrupt request signals. The request channels are maskable so that individual channels can be selectively disabled. All interrupt requests can be programmed in the CIM to be of either type:

- Fast interrupt request (FIQ)
- Normal interrupt request (IRQ)

The precedences of request channels decrease with ascending channel order in the CIM (0 [highest] and 31 [lowest] priority). For these channel priorities and the associated modules, see [Table 6](#).

**Table 6. Interrupt Priority**

MODULES	INTERRUPT SOURCES	INTERRUPT LEVEL/CHANNEL
SPI1	SPI1 end-transfer/overrun	0
RTI	COMP2 interrupt	1
RTI	COMP1 interrupt	2
RTI	TAP interrupt	3
SPI2	SPI2 end-transfer/overrun	4
GIO	Interrupt A	5
Reserved		6
HET	Interrupt A	7
Reserved		8
SCI1/SCI2	SCI1/SCI2 error interrupt	9
SCI1	SCI1 receive interrupt	10
C2Sla	C2Sla interrupt	11
Reserved		12
Reserved		13
SCC	Interrupt A	14
Reserved		15
MibADC	End event conversion	16
SCI2	SCI2 receive interrupt	17
Reserved		18
Reserved		19
SCI1	SCI1 transmit interrupt	20
System	SW interrupt (SSI)	21
Reserved		22
HET	Interrupt B	23
Reserved		24
SCC	Interrupt B	25
SCI2	SCI2 transmit interrupt	26
MibADC	End Group1 conversion	27
Reserved		28
GIO	Interrupt B	29
MibADC	End Group2 conversion	30
Reserved		31

## MibADC

The multi-buffered analog-to-digital converter (MibADC) accepts an analog signal and converts the signal to a 10-bit digital value.

The A128 MibADC module can function in two modes: compatibility mode, where its programmer's model is compatible with the TMS470R1x ADC module and its digital results are stored in digital result registers; or in buffered mode, where the digital result registers are replaced with three FIFO buffers, one for each conversion group [event, group1 (G1), and group2 (G2)]. In buffered mode, the MibADC buffers can be serviced by interrupts.

### *MibADC Event Trigger Enhancements*

The MibADC includes two major enhancements over the event-triggering capability of the TMS470R1x ADC.

- Both group1 and the event group can be configured for event-triggered operation, providing up to two event-triggered groups.
- The trigger source and polarity can be selected individually for both group1 and the event group from the three options identified in [Table 7](#).

**Table 7. MibADC Event Hookup Configuration**

EVENT #	SOURCE SELECT BITS for G1 or EVENT (G1SRC[1:0] or EVSRC[1:0])	SIGNAL PIN NAME
EVENT1	00	ADEVT
EVENT2	01	HET18
EVENT3	10	HET19
EVENT4	11	reserved

For group1, these event-triggered selections are configured via the group1 source select bits (G1SRC[1:0]) in the AD event source register (ADEVTSRC[5:4]). For the event group, these event-triggered selections are configured via the event group source select bits (EVSRC[1:0]) in the AD event source register (ADEVTSRC[1:0]).

For more detailed functional information on the MibADC, see the *TMS470R1x Multi-Buffered Analog-to-Digital Converter (MibADC) Reference Guide* (literature number SPNU206).

## Documentation Support

Extensive documentation supports all of the TMS470 microcontroller family of devices. The types of documentation available include data sheets with design specifications; complete user's guides for all devices and development support tools; and hardware and software application notes. Useful reference documentation includes:

- Bulletin
  - *TMS470 Microcontroller Family Product Bulletin* (literature number SPNB086)
- User's Guides
  - *TMS470R1x System Module Reference Guide* (literature number SPNU189)
  - *TMS470R1x GeneralPurpose Input/Output (GPIO) Reference Guide* (literature number SPNU192)
  - *TMS470R1x Direct Memory Access (DMA) Controller Reference Guide* (literature number SPNU194)
  - *TMS470R1x Serial Peripheral Interface (SPI) Reference Guide* (literature number SPNU195)
  - *TMS470R1x Serial Communication Interface (SCI) Reference Guide* (literature number SPNU196)
  - *TMS470R1x Controller Area Network (CAN) Reference Guide* (literature number SPNU197)
  - *TMS470R1x HighEnd Timer (HET) Reference Guide* (literature number SPNU199)
  - *TMS470R1x External Clock Prescale (ECP) Reference Guide* (literature number SPNU202)
  - *TMS470R1x MultiBuffered AnalogtoDigital (MibADC) Reference Guide* (literature number SPNU206)
  - *TMS470R1x ZeroPin PhaseLocked Loop (ZPLL) Clock Module Reference Guide* (literature number SPNU212)
  - *TMS470R1x F05 Flash Reference Guide* (literature number SPNU213)
  - *TMS470R1x Class II Serial Interface B (C2SIb) Reference Guide* (literature number SPNU214)
  - *TMS470R1x Class II Serial Interface A (C2SIa) Reference Guide* (literature number SPNU218)
  - *TMS470R1x Inter-Integrated Circuit (I2C) Reference Guide* (literature number SPNU223)
  - *TMS470 Peripherals Overview Reference Guide* (literature number SPNU248)
- Errata Sheet:
  - *TMS470R1A128 TMS470 Microcontrollers Silicon Errata* (literature number SPNZ132)

### Device and Development-Support Tool Nomenclature

To designate the stages in the product development cycle, TI assigns prefixes to the part numbers of all DSP devices and support tools. Each DSP commercial family member has one of three prefixes: TMX, TMP, or TMS (e.g., **TMS470R1A128**). Texas Instruments recommends two of three possible prefix designators for its support tools: TMDX and TMDS. These prefixes represent evolutionary stages of product development from engineering prototypes (TMX/TMDX) through fully qualified production devices/tools (TMS/TMDS).

Device development evolutionary flow:

- TMX** Experimental device that is not necessarily representative of the final device's electrical specifications
- TMP** Final silicon die that conforms to the device's electrical specifications but has not completed quality and reliability verification
- TMS** Fully qualified production device

Support tool development evolutionary flow:

- TMDX** Development-support product that has not yet completed Texas Instruments internal qualification testing.
- TMDS** Fully qualified development-support product

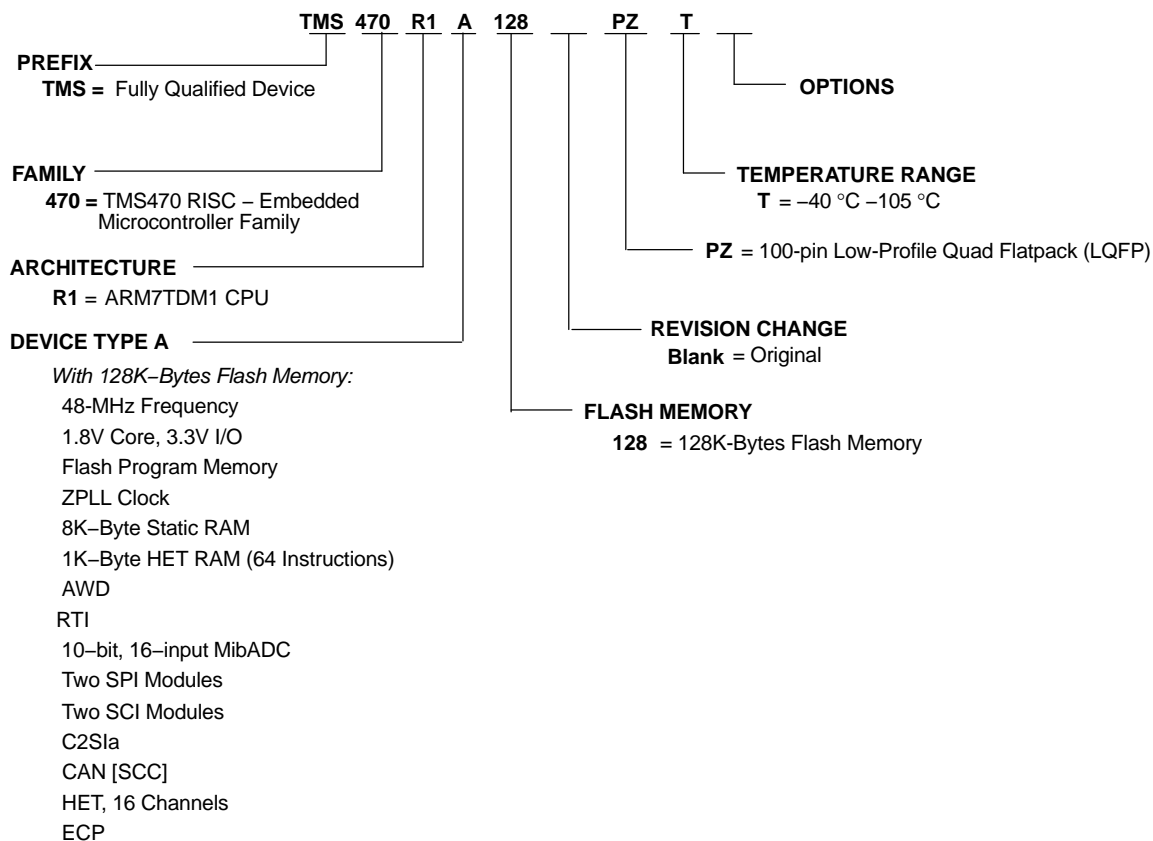
TMX and TMP devices and TMDX development-support tools are shipped against the following disclaimer:

"Developmental product is intended for internal evaluation purposes."

TMS devices and TMDS development-support tools have been characterized fully, and the quality and reliability of the device have been demonstrated fully. TI's standard warranty applies.

Predictions show that prototype devices (TMX or TMP) have a greater failure rate than the standard production devices. Texas Instruments recommends that these devices not be used in any production system because their expected end-use failure rate still is undefined. Only qualified production devices are to be used.

[Figure 2](#) illustrates the numbering and symbol nomenclature for the TMS470R1x family.

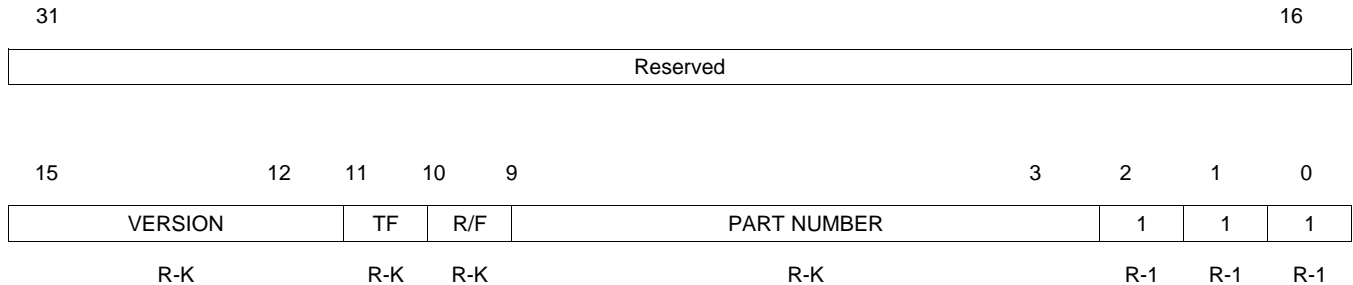


**Figure 2. TMS470R1x Family Nomenclature**

**Device Identification Code Register**

The device identification code register identifies the silicon version, the technology family (TF), a ROM or flash device, and an assigned device-specific part number (see [Figure 3](#) and [Table 8](#)). The A128 device identification code register value is 0xn83F.

**Figure 3. TMS470 Device ID Bit Allocation Register [offset = FFFF\_FF0]**



**LEGEND:**

For bits 3-15: R = Read only, -K = Value constant after RESET

For bits 0-2: R = Read only, -1 = Value after RESET

**Table 8. TMS Device ID Bit Allocation Register Field Description**

Bit	Name	Value	Description
31–16	Reserved		Reads are undefined and writes have no effect.
15–12	VERSION		Silicon version (revision) These bits identify the silicon version of the device.
11	TF	0 1	Technology family This bit distinguishes the technology family core power supply. 3.3 V for F10/C10 devices 1.8 V for F05/C05 devices
10	R/F	0 1	ROM/Flash This bit distinguishes between ROM and flash devices: Flash device ROM device
9–3	PART NUMBER		Device-specific part number These bits identify the assigned device-specific part number. The assigned device-specific part number for the A128 devices is 0000111.
2–0	1		Mandatory High Bits 2, 1, and 0 are tied high by default.

## DEVICE ELECTRICAL SPECIFICATIONS AND TIMING PARAMETERS

### Absolute Maximum Ratings

over operating free-air temperature range<sup>(1)</sup>

Supply voltage ranges:	$V_{CC}$ <sup>(2)</sup>	-0.5 V to 2.5 V
Supply voltage ranges:	$V_{CCIO}$ , $V_{CCAD}$ , $V_{CCP}$ (Flash pump) <sup>(2)</sup>	-0.5 V to 4.1 V
Input voltage range:	All input pins	-0.5 V to 4.1 V
Input clamp current:	$I_{IK}$ ( $V_I < 0$ or $V_I > V_{CCIO}$ )	
	All pins except ADIN[0:11], $\overline{PORRST}$ , $\overline{TRST}$ , TEST and TCK	±20 mA
	$I_{IK}$ ( $V_I < 0$ or $V_I > V_{CCAD}$ )	
	ADIN[0:11]	±10 mA
Operating free-air temperature ranges, $T_A$ :	T version	-40°C to 105°C
Operating junction temperature range, $T_J$		-40°C to 150°C
Storage temperature range, $T_{stg}$		-65°C to 150°C

- (1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the devices at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) All voltage values are with respect to their associated grounds.

### Device Recommended Operating Conditions<sup>(1)</sup>

		MIN	NOM	MAX	UNIT
$V_{CC}$	Digital logic (and flash supply voltage for A128) (Core)	1.81		2.06	V
$V_{CCIO}$	Digital logic supply voltage (I/O)	3	3.3	3.6	V
$V_{CCAD}$	ADC supply voltage	3	3.3	3.6	V
$V_{CCP}$	Flash pump supply voltage	3	3.3	3.6	V
$V_{SS}$	Digital logic supply ground		0		V
$V_{SSAD}$	ADC supply ground	-0.1		0.1	V
$T_A$	Operating free-air temperature	-40		105	°C
$T_J$	Operating junction temperature	-40		150	°C

- (1) All voltages are with respect to  $V_{SS}$ , except  $V_{CCAD}$ , which is with respect to  $V_{SSAD}$ .

**Electrical Characteristics over Recommended Operating Free-Air Temperature Range<sup>(1)</sup>**

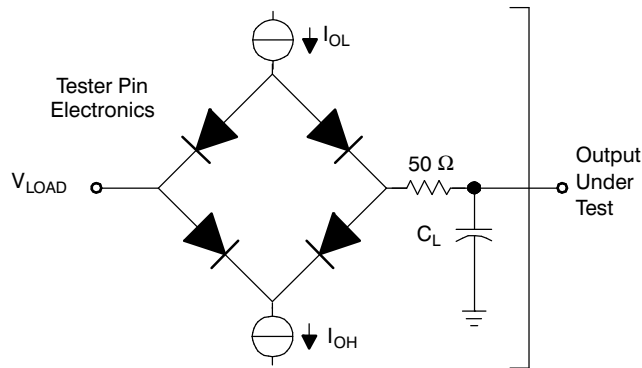
PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>hys</sub>	Input hysteresis		0.15			V
V <sub>IL</sub>	Low-level input voltage	All inputs <sup>(2)</sup> except OSCIN	-0.3		0.8	V
		OSCIN only	-0.3		0.35 V <sub>CC</sub>	
V <sub>IH</sub>	High-level input voltage	All inputs except OSCIN	2		V <sub>CCIO</sub> + 0.3	V
		OSCIN only	0.65 V <sub>CC</sub>		V <sub>CC</sub> + 0.3	
V <sub>th</sub>	Input threshold voltage	AWD only	1.35		1.8	V
RDS <sub>ON</sub>	Drain to source on resistance	AWD only <sup>(3)</sup>	V <sub>OL</sub> = 0.35 V @ I <sub>OL</sub> = 8 mA		45	Ω
V <sub>OL</sub>	Low-level output voltage <sup>(4)</sup>	I <sub>OL</sub> = I <sub>OL</sub> MAX			0.2 V <sub>CCIO</sub>	V
		I <sub>OL</sub> = 50 μA			0.2	
V <sub>OH</sub>	High-level output voltage <sup>(4)</sup>	I <sub>OH</sub> = I <sub>OH</sub> MIN	0.8 V <sub>CCIO</sub>			V
		I <sub>OH</sub> = 50 μA	V <sub>CCIO</sub> - 0.2			
I <sub>IC</sub>	Input clamp current (I/O pins) <sup>(5)</sup>	V <sub>I</sub> < V <sub>SSIO</sub> - 0.3 or V <sub>I</sub> > V <sub>CCIO</sub> + 0.3	-2		2	mA
I <sub>I</sub>	Input current (I/O pins)	I <sub>IL</sub> Pulldown	V <sub>I</sub> = V <sub>SS</sub>	-1	1	μA
		I <sub>IH</sub> Pulldown	V <sub>I</sub> = V <sub>CCIO</sub>	5	40	
		I <sub>IL</sub> Pullup	V <sub>I</sub> = V <sub>SS</sub>	-40	-5	
		I <sub>IH</sub> Pullup	V <sub>I</sub> = V <sub>CCIO</sub>	-1	1	
		All other pins	No pullup or pulldown	-1	1	
I <sub>OL</sub>	Low-level output current	CLKOUT, AWD, TDO	V <sub>OL</sub> = V <sub>OL</sub> MAX		8	mA
		RST, SPI1CLK, SPI1SOMI, SPI1SIMO, SPI2CLK, SPI2SOMI, SPI2SIMO	V <sub>OL</sub> = V <sub>OL</sub> MAX		4	
		All other output pins <sup>(6)</sup>	V <sub>OL</sub> = V <sub>OL</sub> MAX		2	
I <sub>OH</sub>	High-level output current	CLKOUT, TDO	V <sub>OH</sub> = V <sub>OH</sub> MIN	-8		mA
		SPI1CLK, SPI1SOMI, SPI1SIMO, SPI2CLK, SPI2SOMI, SPI2SIMO	V <sub>OH</sub> = V <sub>OH</sub> MIN	-4		
		All other output pins except RST <sup>(6)</sup>	V <sub>OH</sub> = V <sub>OH</sub> MIN	-2		
I <sub>CC</sub>	V <sub>CC</sub> Digital supply current (operating mode)	Pipeline	SYSCLK = 48 MHz, ICLK = 24 MHz, V <sub>CC</sub> = 2.06 V		70	mA
		Non-pipeline	SYSCLK = 28 MHz, ICLK = 14 MHz, V <sub>CC</sub> = 2.06 V		50	mA
	V <sub>CC</sub> Digital supply current (standby mode) <sup>(7)</sup>		OSCIN = 6 MHz, V <sub>CC</sub> = 2.06 V		3.0	mA
	V <sub>CC</sub> Digital supply current (halt mode) <sup>(7)</sup>		All frequencies, V <sub>CC</sub> = 2.06 V		1.0	mA
I <sub>CCIO</sub>	V <sub>CCIO</sub> Digital supply current (operating mode)		No DC load, V <sub>CCIO</sub> = 3.6 V <sup>(8)</sup>		10	mA
	V <sub>CCIO</sub> Digital supply current (standby mode)		No DC load, V <sub>CCIO</sub> = 3.6 V <sup>(8)</sup>		300	μA
	V <sub>CCIO</sub> Digital supply current (halt mode)		No DC load, V <sub>CCIO</sub> = 3.6 V <sup>(8)</sup>		300	μA

- (1) Source currents (out of the device) are negative while sink currents (into the device) are positive.
- (2) This does not apply to the PORRST pin. For PORRST exceptions, see the RST and PORRST timings section.
- (3) These values help to determine the external RC network circuit. For more details, see the *TMS470R1x System Module Reference Guide* (literature number SPNU189).
- (4) V<sub>OL</sub> and V<sub>OH</sub> are linear with respect to the amount of load current (I<sub>OL</sub>/I<sub>OH</sub>) applied.
- (5) Parameter does not apply to input-only or output-only pins.
- (6) The 2 mA buffers on these devices are called zero-dominant buffers. If two of these buffers are shorted together and one is outputting a low level and the other is outputting a high level, the resulting value will always be low.
- (7) For flash banks/pumps in sleep mode.
- (8) I/O pins configured as inputs or outputs with no load. All pulldown inputs ≤ 0.2 V. All pullup inputs ≥ V<sub>CCIO</sub> - 0.2 V.

**Electrical Characteristics over Recommended Operating Free-Air Temperature Range (continued)**

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
$I_{CCAD}$	$V_{CCAD}$ supply current (operating mode)	All frequencies, $V_{CCAD} = 3.6$ V			15	mA
	$V_{CCAD}$ supply current (standby mode)	All frequencies, $V_{CCAD} = 3.6$ V			20	$\mu$ A
	$V_{CCAD}$ supply current (halt mode)	All frequencies, $V_{CCAD} = 3.6$ V			20	$\mu$ A
$I_{CCP}$	$V_{CCP}$ pump supply current	$V_{CCP} = 3.6$ V read operation			50	mA
		$V_{CCP} = 3.6$ V program and erase			70	mA
		$V_{CCP} = 3.6$ V standby mode operation <sup>(7)</sup>			20	$\mu$ A
		$V_{CCP} = 3.6$ V halt mode operation <sup>(7)</sup>			20	$\mu$ A
$C_I$	Input capacitance			2	pF	
$C_O$	Output capacitance			3	pF	

**Parameter Measurement Information**



Where:  $I_{OL}$  =  $I_{OL}$  MAX for the respective pin<sup>(A)</sup>  
 $I_{OH}$  =  $I_{OH}$  MIN for the respective pin<sup>(A)</sup>  
 $V_{LOAD}$  = 1.5 V  
 $C_L$  = 150-pF typical load-circuit capacitance<sup>(B)</sup>

- A. For these values, see the "Electrical Characteristics over Recommended Operating Free-Air Temperature Range" table.
- B. All timing parameters measured using an external load capacitance of 150 pF unless otherwise noted.

**Figure 4. Test Load Circuit**

## Timing Parameter Symbolology

Timing parameter symbols have been created in accordance with JEDEC Standard 100. To shorten the symbols, some of the pin names and other related terminology have been abbreviated as follows:

CM	Compaction, CMPCT	RD	Read
CO	CLKOUT	RST	Reset, $\overline{\text{RST}}$
ER	Erase	RX	SCInRX
ICLK	Interface clock	S	Slave mode
M	Master mode	SCC	SCInCLK
OSC, OSC1	OSCIN	SIMO	SPInSIMO
OSCO	OSCOU	SOMI	SPInSOMI
P	Program, PROG	SPC	SPInCLK
R	Ready	SYS	System clock
R0	Read margin 0, RDMRGN0	TX	SCInTX
R1	Read margin 1, RDMRGN1		

Lowercase subscripts and their meanings are:

a	access time	r	rise time
c	cycle time (period)	su	setup time
d	delay time	t	transition time
f	fall time	v	valid time
h	hold time	w	pulse duration (width)

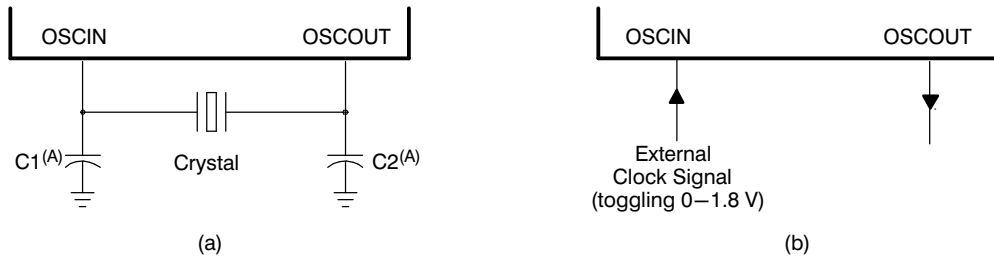
The following additional letters are used with these meanings:

H	High	X	Unknown, changing, or don't care level
L	Low	Z	High impedance
V	Valid		

### External Reference Resonator/Crystal Oscillator Clock Option

The oscillator is enabled by connecting the appropriate fundamental 4–20 MHz resonator/crystal and load capacitors across the external OSCIN and OSCOUT pins as shown in Figure 5a. The oscillator is a single-stage inverter held in bias by an integrated bias resistor. This resistor is disabled during leakage test measurement and HALT mode. **TI strongly encourages each customer to submit samples of the device to the resonator/crystal vendors for validation.** The vendors are equipped to determine what load capacitors will best tune their resonator/crystal to the microcontroller device for optimum start-up and operation over temperature/voltage extremes.

An external oscillator source can be used by connecting a 1.8-V clock signal to the OSCIN pin and leaving the OSCOUT pin unconnected (open) as shown in Figure 5b.



- A. The values of C1 and C2 should be provided by the resonator/crystal vendor.

**Figure 5. Crystal/Clock Connection**

## ZPLL AND CLOCK SPECIFICATIONS

### Timing Requirements for ZPLL Circuits Enabled or Disabled

		MIN	MAX	UNIT
$f_{(OSC)}$	Input clock frequency	4	20	MHz
$t_{c(Osc)}$	Cycle time, OSCIN	50		ns
$t_{w(OscIL)}$	Pulse duration, OSCIN low	15		ns
$t_{w(OscIH)}$	Pulse duration, OSCIN high	15		ns
$f_{(OSCRST)}$	OSC FAIL frequency <sup>(1)</sup>		53	kHz

- (1) Causes a device reset (specifically a clock reset) by setting the RST OSC FAIL (GLBCTRL.15) and the OSC FAIL flag (GLBSTAT.1) bits equal to 1. For more detailed information on these bits and device resets, see the *TMS470R1x System Module Reference Guide* (literature number SPNU189).

### Switching Characteristics over Recommended Operating Conditions for Clocks<sup>(1)(2)</sup>

PARAMETER		TEST CONDITIONS <sup>(3)</sup>	MIN	MAX	UNIT
$f_{(SYS)}$	System clock frequency <sup>(4)</sup>	Pipeline mode enabled		48	MHz
		Pipeline mode disabled		28	
$f_{(CONFIG)}$	System clock frequency - flash config mode			24	MHz
$f_{(ICLK)}$	Interface clock frequency	Pipeline mode enabled		25	MHz
		Pipeline mode disabled		24	
$f_{(ECLK)}$	External clock output frequency for ECP Module	Pipeline mode enabled		25	MHz
		Pipeline mode disabled		24	
$t_{c(SYS)}$	Cycle time, system clock	Pipeline mode enabled	20.8		ns
		Pipeline mode disabled	35.7		
$t_{c(CONFIG)}$	Cycle time, system clock - flash config mode		41.6		ns
$t_{c(ICLK)}$	Cycle time, interface clock	Pipeline mode enabled	40		ns
		Pipeline mode disabled	41.6		
$t_{c(ECLK)}$	Cycle time, ECP module external clock output	Pipeline mode enabled	40		ns
		Pipeline mode disabled	41.6		

- (1)  $f_{(SYS)} = M \times f_{(OSC)} / R$ , where  $M = \{4 \text{ or } 8\}$ ,  $R = \{1,2,3,4,5,6,7,8\}$  when  $PLLDIS = 0$ . R is the system-clock divider determined by the CLKDIVPRE [2:0] bits in the global control register (GLBCTRL[2:0]) and M is the PLL multiplier determined by the MULT4 bit, also in the GLBCTRL register (GLBCTRL[3]).  
 $f_{(SYS)} = f_{(OSC)} / R$ , where  $R = \{1,2,3,4,5,6,7,8\}$  when  $PLLDIS = 1$ .  
 $f_{(ICLK)} = f_{(SYS)} / X$ , where  $X = \{1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16\}$ . X is the interface clock divider ratio determined by the PCR0[4:1] bits in the SYS module.
- (2)  $f_{(ECLK)} = f_{(ICLK)} / N$ , where  $N = \{1 \text{ to } 256\}$ . N is the ECP prescale value defined by the ECPCTRL[7:0] register bits in the ECP module.
- (3) Pipeline mode enabled or disabled is determined by the ENPIPE bit (FMREGOPT.0).
- (4) Flash Vread must be set to 5V to achieve maximum system clock frequency.

Switching Characteristics over Recommended Operating Conditions for External Clocks <sup>(1)(2)(3)</sup>

(see Figure 6 and Figure 7)

PARAMETER		TEST CONDITIONS	MIN	MAX	UNIT
$t_{w(COL)}$	Pulse duration, CLKOUT low	SYSCLK or MCLK <sup>(4)</sup>	$0.5t_{c(SYS)} - t_f$		ns
		ICLK, X is even or 1 <sup>(5)</sup>	$0.5t_{c(ICLK)} - t_f$		
		ICLK, X is odd and not 1 <sup>(5)</sup>	$0.5t_{c(ICLK)} + 0.5t_{c(SYS)} - t_f$		
$t_{w(COH)}$	Pulse duration, CLKOUT high	SYSCLK or MCLK <sup>(4)</sup>	$0.5t_{c(SYS)} - t_f$		ns
		ICLK, X is even or 1 <sup>(5)</sup>	$0.5t_{c(ICLK)} - t_f$		
		ICLK, X is odd and not 1 <sup>(5)</sup>	$0.5t_{c(ICLK)} - 0.5t_{c(SYS)} - t_f$		
$t_{w(EOL)}$	Pulse duration, ECLK low	N is even and X is even or odd	$0.5t_{c(ECLK)} - t_f$		ns
		N is odd and X is even			
		N is odd and X is odd and not 1	$0.5t_{c(ECLK)} + 0.5t_{c(SYS)} - t_f$		
$t_{w(EOH)}$	Pulse duration, ECLK high	N is even and X is even or odd	$0.5t_{c(ECLK)} - t_f$		ns
		N is odd and X is even			
		N is odd and X is odd and not 1	$0.5t_{c(ECLK)} - 0.5t_{c(SYS)} - t_f$		

- (1)  $X = \{1,2,3,4,5,6,7,8,9,10,11,12,13,14,15,16\}$ . X is the interface clock divider ratio determined by the PCR0[4:1] bits in the SYS module.
- (2)  $N = \{1 \text{ to } 256\}$ . N is the ECP prescale value defined by the ECPCTRL[7:0] register bits in the ECP module.
- (3) CLKOUT/ECLK pulse durations (low/high) are a function of the OSCIN pulse durations when PLLDIS is active.
- (4) Clock source bits selected as either SYSCLK (CLKCNTL[6:5] = 11 binary) or MCLK (CLKCNTL[6:5] = 10 binary).
- (5) Clock source bits selected as ICLK (CLKCNTL[6:5] = 01 binary).

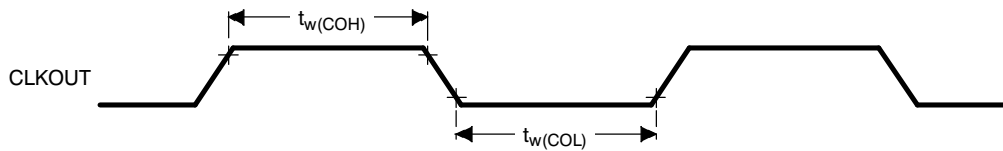


Figure 6. CLKOUT Timing Diagram

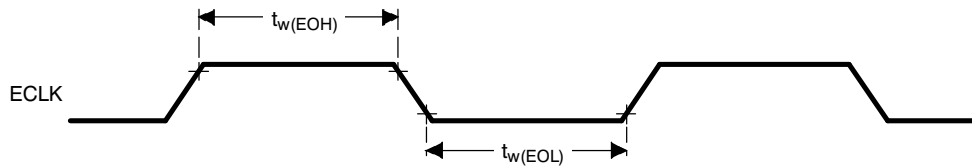


Figure 7. ECLK Timing Diagram

## RST AND PORRST TIMINGS

### Timing Requirements for PORRST

(see Figure 8)

		MIN	MAX	UNIT
$V_{CCPORL}$	$V_{CC}$ low supply level when $\overline{PORRST}$ must be active during power up		0.6	V
$V_{CCPORH}$	$V_{CC}$ high supply level when $\overline{PORRST}$ must remain active during power up and become active during power down	1.5		V
$V_{CCIOPORL}$	$V_{CCIO}$ low supply level when $\overline{PORRST}$ must be active during power up		1.1	V
$V_{CCIOPORH}$	$V_{CCIO}$ high supply level when $\overline{PORRST}$ must remain active during power up and become active during power down	2.75		V
$V_{IL}$	Low-level input voltage after $V_{CCIO} > V_{CCIOPORH}$		$0.2 V_{CCIO}$	V
$V_{IL(PORRST)}$	Low-level input voltage of $\overline{PORRST}$ before $V_{CCIO} > V_{CCIOPORL}$		0.5	V
$t_{su(PORRST)r}$	Setup time, $\overline{PORRST}$ active before $V_{CCIO} > V_{CCIOPORL}$ during power up	0		ms
$t_{su(VCCIO)r}$	Setup time, $V_{CCIO} > V_{CCIOPORL}$ before $V_{CC} > V_{CCPORL}$	0		ms
$t_h(PORRST)r$	Hold time, $\overline{PORRST}$ active after $V_{CC} > V_{CCPORH}$	1		ms
$t_{su(PORRST)f}$	Setup time, $\overline{PORRST}$ active before $V_{CC} \leq V_{CCPORH}$ during power down	8		$\mu$ s
$t_h(PORRST)rio$	Hold time, $\overline{PORRST}$ active after $V_{CC} > V_{CCIOPORH}$	1		ms
$t_h(PORRST)d$	Hold time, $\overline{PORRST}$ active after $V_{CC} < V_{CCPORL}$	0		ms
$t_{su(PORRST)rio}$	Setup time, $\overline{PORRST}$ active before $V_{CC} \leq V_{CCIOPORH}$ during power down	0		ns
$t_{su(VCCIO)f}$	Setup time, $V_{CC} < V_{CCPORL}$ before $V_{CCIO} < V_{CCIOPORL}$	0		ns

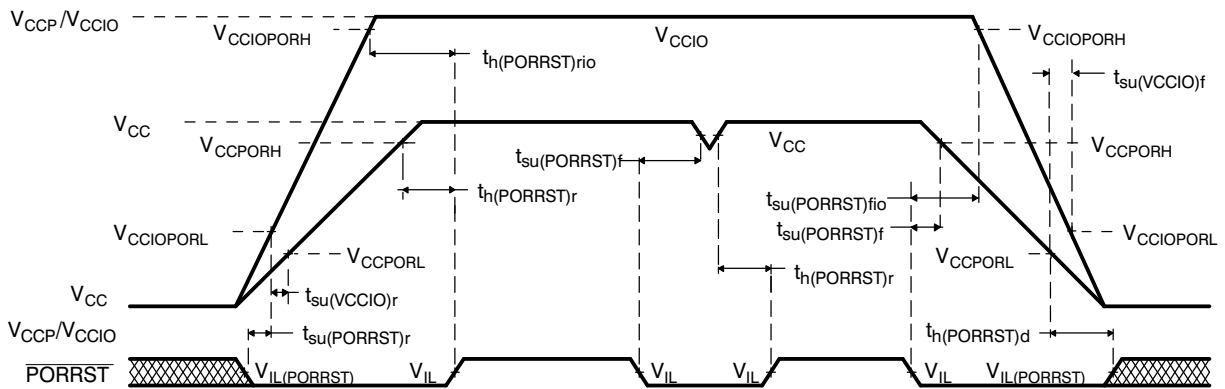


Figure 8.  $\overline{PORRST}$  Timing Diagram

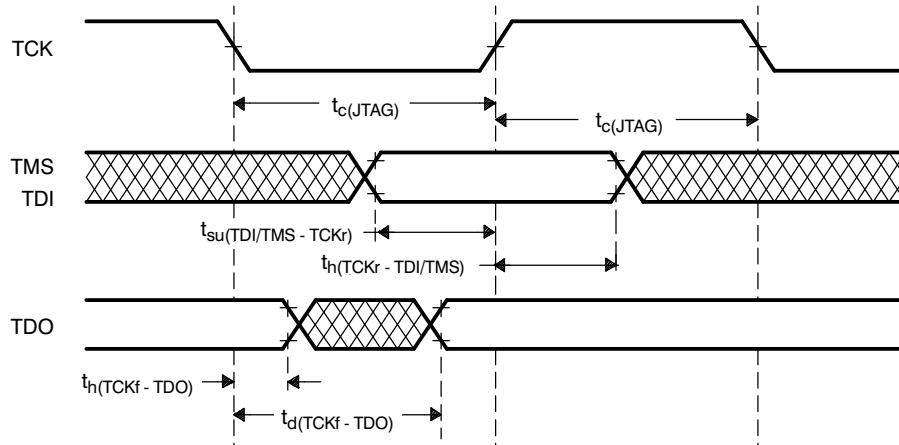
### Switching Characteristics over Recommended Operating Conditions for $\overline{RST}^{(1)}$

PARAMETER		MIN	MAX	UNIT
$t_{v(RST)}$	Valid time, $\overline{RST}$ active after $\overline{PORRST}$ inactive	4112		ns
	Valid time, $\overline{RST}$ active (all others)	8		
$t_{fsu}$	Flash start up time, from $\overline{RST}$ inactive to fetch of first instruction from flash (flash pump stabilization time)	336		ns

(1) Specified values do NOT include rise/fall times. For rise and fall timings, see the "Switching Characteristics for Output Timings versus Load Capacitance" table.

**JTAG Scan Interface Timing (JTAG Clock Specification 10-MHz and 50-pF Load on TDO Output)**

		MIN	MAX	UNIT
$t_{c(JTAG)}$	Cycle time, JTAG low and high period	50		ns
$t_{su(TDI/TMS - TCKr)}$	Setup time, TDI, TMS before TCK rise (TCKr)	15		ns
$t_h(TCKr - TDI/TMS)$	Hold time, TDI, TMS after TCKr	15		ns
$t_h(TCKf - TDO)$	Hold time, TDO after TCKf	10		ns
$t_d(TCKf - TDO)$	Delay time, TDO valid after TCK fall (TCKf)		45	ns



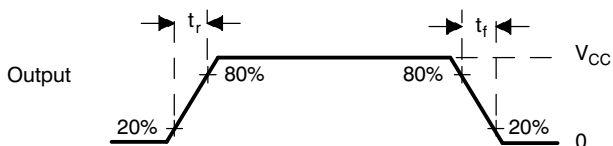
**Figure 9. JTAG Scan Timings**

## OUTPUT TIMINGS

### Switching Characteristics for Output Timings versus Load Capacitance ( $C_L$ )

(see Figure 10)

PARAMETER		MIN	MAX	UNIT	
$t_r$	Rise time, CLKOUT, AWD, TDO	$C_L = 15 \text{ pF}$	0.5	2.50	ns
		$C_L = 50 \text{ pF}$	1.5	5	
		$C_L = 100 \text{ pF}$	3	9	
		$C_L = 150 \text{ pF}$	4.5	12.5	
$t_f$	Fall time, CLKOUT, AWD, TDO	$C_L = 15 \text{ pF}$	0.5	2.5	ns
		$C_L = 50 \text{ pF}$	1.5	5	
		$C_L = 100 \text{ pF}$	3	9	
		$C_L = 150 \text{ pF}$	4.5	12.5	
$t_f$	Rise time, SPI1CLK, SPI1SOMI, SPI1SIMO, SPI2CLK, SPI2SOMI, SPI2SIMO	$C_L = 15 \text{ pF}$	2.5	8	ns
		$C_L = 50 \text{ pF}$	5	14	
		$C_L = 100 \text{ pF}$	9	23	
		$C_L = 150 \text{ pF}$	13	32	
$t_f$	Fall time, $\overline{\text{RST}}$ , SPI1CLK, SPI1SOMI, SPI1SIMO, SPI2CLK, SPI2SOMI, SPI2SIMO	$C_L = 15 \text{ pF}$	2.5	8	ns
		$C_L = 50 \text{ pF}$	5	14	
		$C_L = 100 \text{ pF}$	9	23	
		$C_L = 150 \text{ pF}$	13	32	
$t_r$	Rise time, all other output pins	$C_L = 15 \text{ pF}$	2.5	10	ns
		$C_L = 50 \text{ pF}$	6.0	25	
		$C_L = 100 \text{ pF}$	12	45	
		$C_L = 150 \text{ pF}$	18	65	
$t_f$	Fall time, all other output pins	$C_L = 15 \text{ pF}$	3	10	ns
		$C_L = 50 \text{ pF}$	8.5	25	
		$C_L = 100 \text{ pF}$	16	45	
		$C_L = 150 \text{ pF}$	23	65	



**Figure 10. CMOS-Level Outputs**

## INPUT TIMINGS

### Timing Requirements for Input Timings<sup>(1)</sup>

(see Figure 11)

		MIN	MAX	UNIT
$t_{pw}$	Input minimum pulse width	$t_{c(ICKL)} + 10$		ns

(1)  $t_{c(ICKL)}$  = interface clock cycle time =  $1/f_{(ICKL)}$

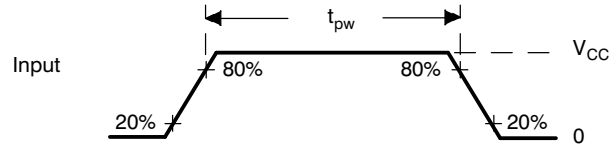


Figure 11. CMOS-Level Inputs

## FLASH TIMINGS

### Timing Requirements for Program Flash<sup>(1)</sup>

		MIN	TYP	MAX	UNIT
$t_{prog(16-bit)}$	Half word (16-bit) programming time	4	16	200	$\mu$ s
$t_{prog(Total)}$	128K-byte programming time <sup>(2)</sup>		1	4	s
$t_{erase(sector)}$	Sector erase time		2	15	s
$t_{wec}$	Write/erase cycles at $T_A = 85^\circ\text{C}$			100	cycles
$t_{fp(\overline{RST})}$	Flash pump settling time from $\overline{RST}$ to SLEEP		$67t_{c(SY S)}$		ns
$t_{fp(SLEEP)}$	Initial flash pump settling time from SLEEP to STANDBY		$67t_{c(SY S)}$		ns
$t_{fp(STANDBY)}$	Initial flash pump settling time from STANDBY to ACTIVE		$34t_{c(SY S)}$		ns

(1) For more detailed information on the flash core sectors, see the *flash program and erase* section of this data sheet.

(2) The 128K-byte programming times include overhead of the state machine.

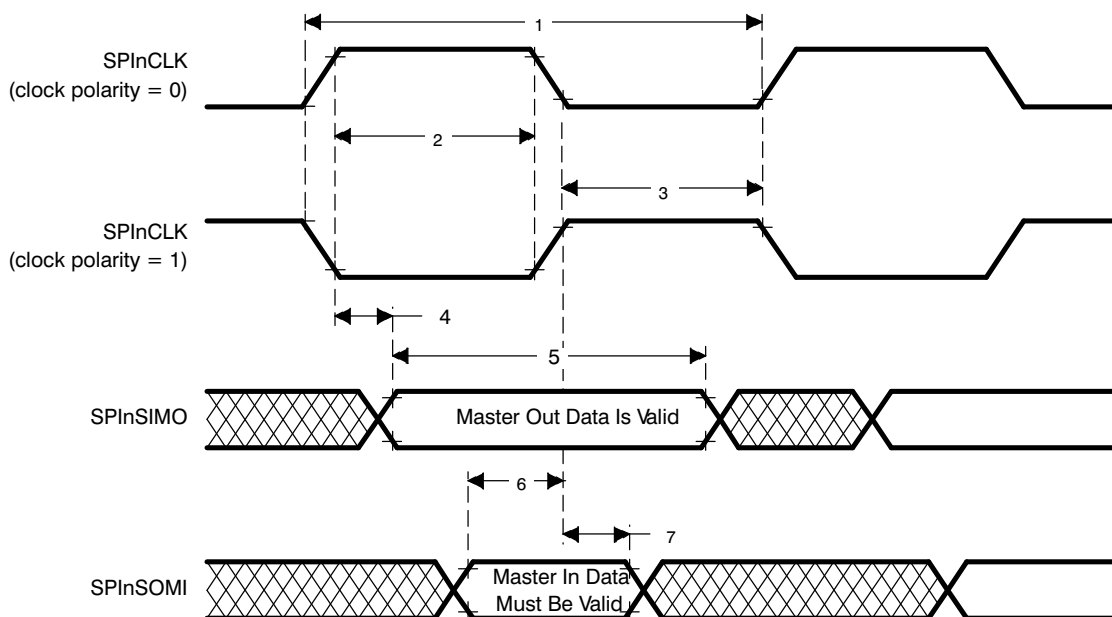
**SPI<sub>n</sub> MASTER MODE TIMING PARAMETERS**

**SPI<sub>n</sub> MASTER MODE EXTERNAL TIMING PARAMETERS<sup>(1)(2)(3)</sup>**

(CLOCK PHASE = 0, SPI<sub>n</sub>CLK = OUTPUT, SPI<sub>n</sub>SIMO = OUTPUT, AND SPI<sub>n</sub>SOMI = INPUT) (see Figure 12)

NO.			MIN	MAX	Unit
1	$t_{c(SPC)M}$	Cycle time, SPI <sub>n</sub> CLK <sup>(4)</sup>	100	$256t_{c(I)CLK}$	ns
2 <sup>(5)</sup>	$t_w(SPCH)M$	Pulse duration, SPI <sub>n</sub> CLK high (clock polarity = 0)	$0.5t_{c(SPC)M} - t_r$	$0.5t_{c(SPC)M} + 5$	ns
	$t_w(SPCL)M$	Pulse duration, SPI <sub>n</sub> CLK low (clock polarity = 1)	$0.5t_{c(SPC)M} - t_f$	$0.5t_{c(SPC)M} + 5$	
3 <sup>(5)</sup>	$t_w(SPCL)M$	Pulse duration, SPI <sub>n</sub> CLK low (clock polarity = 0)	$0.5t_{c(SPC)M} - t_f$	$0.5t_{c(SPC)M} + 5$	ns
	$t_w(SPCH)M$	Pulse duration, SPI <sub>n</sub> CLK high (clock polarity = 1)	$0.5t_{c(SPC)M} - t_r$	$0.5t_{c(SPC)M} + 5$	
4 <sup>(5)</sup>	$t_d(SPCH-SIMO)M$	Delay time, SPI <sub>n</sub> CLK high to SPI <sub>n</sub> SIMO valid (clock polarity = 0)		10	ns
	$t_d(SPCL-SIMO)M$	Delay time, SPI <sub>n</sub> CLK low to SPI <sub>n</sub> SIMO valid (clock polarity = 1)		10	
5 <sup>(5)</sup>	$t_v(SPCL-SIMO)M$	Valid time, SPI <sub>n</sub> SIMO data valid after SPI <sub>n</sub> CLK low (clock polarity = 0)	$t_{c(SPC)M} - 5 - t_f$		ns
	$t_v(SPCH-SIMO)M$	Valid time, SPI <sub>n</sub> SIMO data valid after SPI <sub>n</sub> CLK high (clock polarity = 1)	$t_{c(SPC)M} - 5 - t_r$		
6 <sup>(5)</sup>	$t_{su}(SOMI-SPCL)M$	Setup time, SPI <sub>n</sub> SOMI before SPI <sub>n</sub> CLK low (clock polarity = 0)	6		ns
	$t_{su}(SOMI-SPCH)M$	Setup time, SPI <sub>n</sub> SOMI before SPI <sub>n</sub> CLK high (clock polarity = 1)	6		
7 <sup>(5)</sup>	$t_v(SPCL-SOMI)M$	Valid time, SPI <sub>n</sub> SOMI data valid after SPI <sub>n</sub> CLK low (clock polarity = 0)	4		ns
	$t_v(SPCH-SOMI)M$	Valid time, SPI <sub>n</sub> SOMI data valid after SPI <sub>n</sub> CLK high (clock polarity = 1)	4		

- (1) The MASTER bit (SPI<sub>n</sub>CTRL2.3) is set and the CLOCK PHASE bit (SPI<sub>n</sub>CTRL2.0) is cleared.
- (2)  $t_{c(I)CLK}$  = interface clock cycle time =  $1/f_{(I)CLK}$
- (3) For rise and fall timings, see the "Switching Characteristics for Output Timings versus Load Capacitance" table.
- (4) When the SPI is in Master mode, the following must be true:  
For PS values from 1 to 255:  $t_{c(SPC)M} \geq (PS + 1)t_{c(I)CLK} \geq 100$  ns, where PS is the prescale value set in the SPI<sub>n</sub>CTL1[12:5] register bits.  
For PS values of 0:  $t_{c(SPC)M} = 2t_{c(I)CLK} \geq 100$  ns.
- (5) The active edge of the SPI<sub>n</sub>CLK signal referenced is controlled by the CLOCK POLARITY bit (SPI<sub>n</sub>CTRL2.1).



**Figure 12. SPI<sub>n</sub> Master Mode External Timing (CLOCK PHASE = 0)**

**SPI<sub>IN</sub> MASTER MODE EXTERNAL TIMING PARAMETERS** (1)(2)(3)

(CLOCK PHASE = 1, SPInCLK = OUTPUT, SPInSIMO = OUTPUT, AND SPInSOMI = INPUT) (see Figure 13)

NO.			MIN	MAX	Unit
1	$t_{c(SPC)M}$	Cycle time, SPInCLK (4)	100	$256t_{c(ICLK)}$	ns
2(5)	$t_{w(SPCH)M}$	Pulse duration, SPInCLK high (clock polarity = 0)	$0.5t_{c(SPC)M} - t_r$	$0.5t_{c(SPC)M} + 5$	ns
	$t_{w(SPCL)M}$	Pulse duration, SPInCLK low (clock polarity = 1)	$0.5t_{c(SPC)M} - t_f$	$0.5t_{c(SPC)M} + 5$	
3(5)	$t_{w(SPCL)M}$	Pulse duration, SPInCLK low (clock polarity = 0)	$0.5t_{c(SPC)M} - t_f$	$0.5t_{c(SPC)M} + 5$	ns
	$t_{w(SPCH)M}$	Pulse duration, SPInCLK high (clock polarity = 1)	$0.5t_{c(SPC)M} - t_r$	$0.5t_{c(SPC)M} + 5$	
4(5)	$t_{v(SIMO-SPCH)M}$	Valid time, SPInCLK high after SPInSIMO data valid (clock polarity = 0)	$0.5t_{c(SPC)M} - 10$		ns
	$t_{v(SIMO-SPCL)M}$	Valid time, SPInCLK low after SPInSIMO data valid (clock polarity = 1)	$0.5t_{c(SPC)M} - 10$		
5(5)	$t_{v(SPCH-SIMO)M}$	Valid time, SPInSIMO data valid after SPInCLK high (clock polarity = 0)	$0.5t_{c(SPC)M} - 5 - t_r$		ns
	$t_{v(SPCL-SIMO)M}$	Valid time, SPInSIMO data valid after SPInCLK low (clock polarity = 1)	$0.5t_{c(SPC)M} - 5 - t_f$		
6(5)	$t_{su(SOMI-SPCH)M}$	Setup time, SPInSOMI before SPInCLK high (clock polarity = 0)	6		ns
	$t_{su(SOMI-SPCL)M}$	Setup time, SPInSOMI before SPInCLK low (clock polarity = 1)	6		
7(5)	$t_{v(SPCH-SOMI)M}$	Valid time, SPInSOMI data valid after SPInCLK high (clock polarity = 0)	6		ns
	$t_{v(SPCL-SOMI)M}$	Valid time, SPInSOMI data valid after SPInCLK low (clock polarity = 1)	6		

- (1) The MASTER bit (SPInCTRL2.3) is set and the CLOCK PHASE bit (SPInCTRL2.0) is set.
- (2)  $t_{c(ICLK)}$  = interface clock cycle time =  $1/f_{(ICLK)}$
- (3) For rise and fall timings, see the "Switching Characteristics for Output Timings versus Load Capacitance" table.
- (4) When the SPI is in master mode, the following must be true:  
For PS values from 1 to 255:  $t_{c(SPC)M} \geq (PS + 1)t_{c(ICLK)} \geq 100$  ns, where PS is the prescale value set in the SPInCTL1[12:5] register bits.  
For PS values of 0:  $t_{c(SPC)M} = 2t_{c(ICLK)} \geq 100$  ns.
- (5) The active edge of the SPInCLK signal referenced is controlled by the CLOCK POLARITY bit (SPInCTRL2.1).

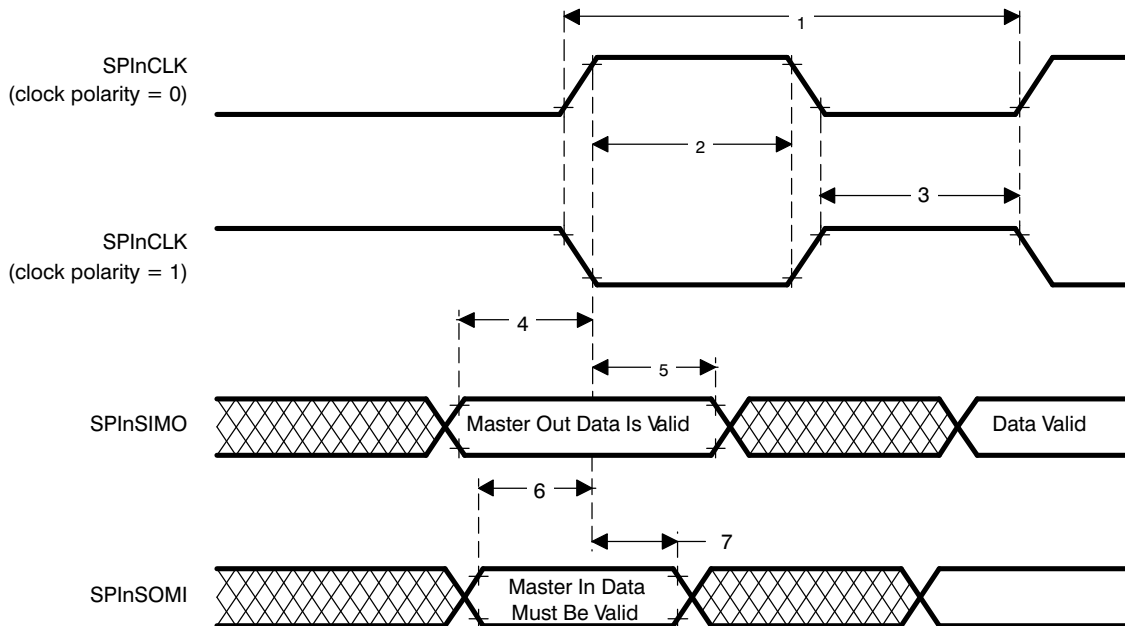


Figure 13. SPI<sub>IN</sub> Master Mode External Timing (CLOCK PHASE = 1)

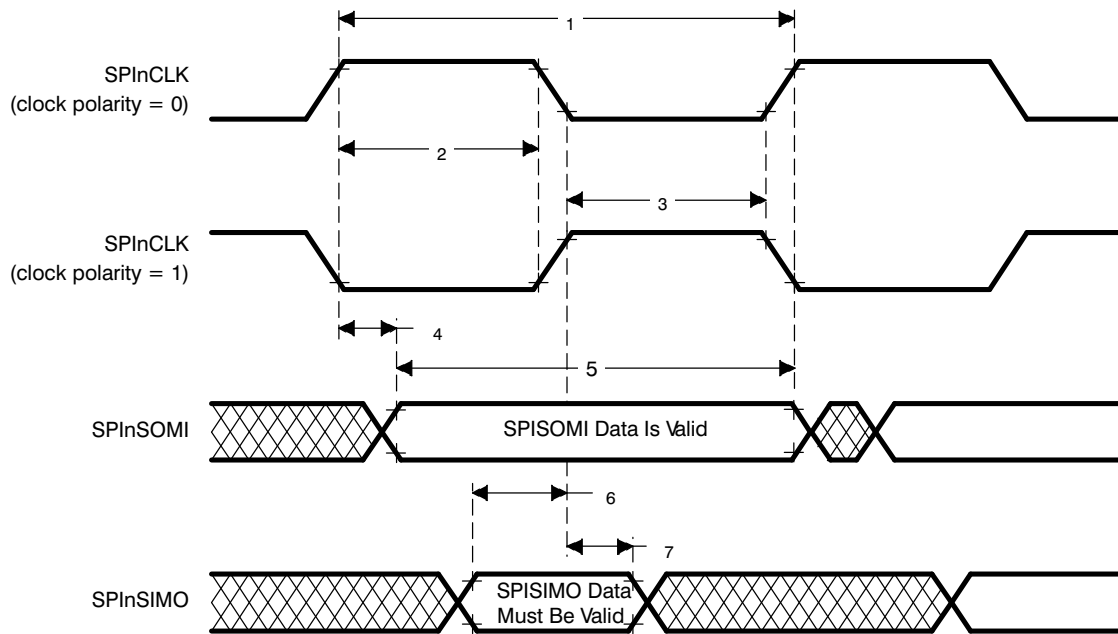
**SPI<sub>n</sub> SLAVE MODE TIMING PARAMETERS**

**SPI<sub>n</sub> SLAVE MODE EXTERNAL TIMING PARAMETERS<sup>(1)(2)(3)(4)</sup>**

(CLOCK PHASE = 0, SPI<sub>n</sub>CLK = INPUT, SPI<sub>n</sub>SIMO = INPUT, AND SPI<sub>n</sub>SOMI = OUTPUT) (see Figure 14)

NO			MIN	MAX	Unit
1	$t_{c(SPC)S}$	Cycle time, SPI <sub>n</sub> CLK <sup>(5)</sup>	100	$256t_{c(I)CLK}$	ns
2 <sup>(6)</sup>	$t_{w(SPCH)S}$	Pulse duration, SPI <sub>n</sub> CLK high (clock polarity = 0)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	ns
	$t_{w(SPCL)S}$	Pulse duration, SPI <sub>n</sub> CLK low (clock polarity = 1)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	
3 <sup>(6)</sup>	$t_{w(SPCL)S}$	Pulse duration, SPI <sub>n</sub> CLK low (clock polarity = 0)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	ns
	$t_{w(SPCH)S}$	Pulse duration, SPI <sub>n</sub> CLK high (clock polarity = 1)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	
4 <sup>(6)</sup>	$t_{d(SPCH-SOMI)S}$	Delay time, SPI <sub>n</sub> CLK high to SPI <sub>n</sub> SOMI valid (clock polarity = 0)		$6 + t_r$	ns
	$t_{d(SPCL-SOMI)S}$	Delay time, SPI <sub>n</sub> CLK low to SPI <sub>n</sub> SOMI valid (clock polarity = 1)		$6 + t_f$	
5 <sup>(6)</sup>	$t_{v(SPCH-SOMI)S}$	Valid time, SPI <sub>n</sub> SOMI data valid after SPI <sub>n</sub> CLK high (clock polarity = 0)	$t_{c(SPC)S} - 6 - t_r$		ns
	$t_{v(SPCL-SOMI)S}$	Valid time, SPI <sub>n</sub> SOMI data valid after SPI <sub>n</sub> CLK low (clock polarity = 1)	$t_{c(SPC)S} - 6 - t_f$		
6 <sup>(6)</sup>	$t_{su(SIMO-SPCL)S}$	Setup time, SPI <sub>n</sub> SIMO before SPI <sub>n</sub> CLK low (clock polarity = 0)	6		ns
	$t_{su(SIMO-SPCH)S}$	Setup time, SPI <sub>n</sub> SIMO before SPI <sub>n</sub> CLK high (clock polarity = 1)	6		
7 <sup>(6)</sup>	$t_{v(SPCL-SIMO)S}$	Valid time, SPI <sub>n</sub> SIMO data valid after SPI <sub>n</sub> CLK low (clock polarity = 0)	6		ns
	$t_{v(SPCH-SIMO)S}$	Valid time, SPI <sub>n</sub> SIMO data valid after SPI <sub>n</sub> CLK high (clock polarity = 1)	6		

- (1) The MASTER bit (SPI<sub>n</sub>CTRL2.3) is cleared and the CLOCK PHASE bit (SPI<sub>n</sub>CTRL2.0) is cleared.
- (2) If the SPI is in slave mode, the following must be true:  $t_{c(SPC)S} \geq (PS + 1)t_{c(I)CLK}$ , where PS = prescale value set in SPI<sub>n</sub>CTL1[12:5].
- (3) For rise and fall timings, see the "Switching Characteristics for Output Timings versus Load Capacitance" table.
- (4)  $t_{c(I)CLK}$  = interface clock cycle time =  $1/f_{(I)CLK}$
- (5) When the SPI<sub>n</sub> is in slave mode, the following must be true:  
 For PS values from 1 to 255:  $t_{c(SPC)S} \geq (PS + 1)t_{c(I)CLK} \geq 100$  ns, where PS is the prescale value set in the SPI<sub>n</sub>CTL1[12:5] register bits.  
 For PS values of 0:  $t_{c(SPC)S} = 2t_{c(I)CLK} \geq 100$  ns.
- (6) The active edge of the SPI<sub>n</sub>CLK signal referenced is controlled by the CLOCK POLARITY bit (SPI<sub>n</sub>CTRL2.1).



**Figure 14. SPIn Slave Mode External Timing (CLOCK PHASE = 0)**

**SPI<sub>IN</sub> SLAVE MODE EXTERNAL TIMING PARAMETERS**<sup>(1)(2)(3)(4)</sup>

(CLOCK PHASE = 1, SPInCLK = INPUT, SPInSIMO = INPUT, AND SPInSOMI = OUTPUT) (see [Figure 15](#))

NO			MIN	MAX	Unit
1	$t_{c(SPC)S}$	Cycle time, SPInCLK <sup>(5)</sup>	100	$256t_{c(I)CLK}$	ns
2 <sup>(6)</sup>	$t_{w(SPCH)S}$	Pulse duration, SPInCLK high (clock polarity = 0)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	ns
	$t_{w(SPCL)S}$	Pulse duration, SPInCLK low (clock polarity = 1)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	
3 <sup>(6)</sup>	$t_{w(SPCL)S}$	Pulse duration, SPInCLK low (clock polarity = 0)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	ns
	$t_{w(SPCH)S}$	Pulse duration, SPInCLK high (clock polarity = 1)	$0.5t_{c(SPC)S} - 0.25t_{c(I)CLK}$	$0.5t_{c(SPC)S} + 0.25t_{c(I)CLK}$	
4 <sup>(6)</sup>	$t_{v(SOMI-SPCH)S}$	Valid time, SPInCLK high after SPInSOMI data valid (clock polarity = 0)	$0.5t_{c(SPC)S} - 6 - t_r$		ns
	$t_{v(SOMI-SPCL)S}$	Valid time, SPInCLK low after SPInSOMI data valid (clock polarity = 1)	$0.5t_{c(SPC)S} - 6 - t_f$		
5 <sup>(6)</sup>	$t_{v(SPCH-SOMI)S}$	Valid time, SPInSOMI data valid after SPInCLK high (clock polarity = 0)	$0.5t_{c(SPC)S} - 6 - t_r$		ns
	$t_{v(SPCL-SOMI)S}$	Valid time, SPInSOMI data valid after SPInCLK low (clock polarity = 1)	$0.5t_{c(SPC)S} - 6 - t_f$		
6 <sup>(6)</sup>	$t_{su(SIMO-SPCH)S}$	Setup time, SPInSIMO before SPInCLK high (clock polarity = 0)	6		ns
	$t_{su(SIMO-SPCL)S}$	Setup time, SPInSIMO before SPInCLK low (clock polarity = 1)	6		
7 <sup>(6)</sup>	$t_{v(SPCH-SIMO)S}$	Valid time, SPInSIMO data valid after SPInCLK high (clock polarity = 0)	6		ns
	$t_{v(SPCL-SIMO)S}$	Valid time, SPInSIMO data valid after SPInCLK low (clock polarity = 1)	6		

- (1) The MASTER bit (SPInCTRL2.3) is cleared and the CLOCK PHASE bit (SPInCTRL2.0) is set.
- (2) If the SPI is in slave mode, the following must be true:  $t_{c(SPC)S} \geq (PS + 1)t_{c(I)CLK}$ , where PS = prescale value set in SPInCTL1[12:5].
- (3) For rise and fall timings, see the "Switching Characteristics for Output Timings versus Load Capacitance" table.
- (4)  $t_{c(I)CLK}$  = interface clock cycle time =  $1/f_{(I)CLK}$
- (5) When the SPIn is in slave mode, the following must be true:  
 For PS values from 1 to 255:  $t_{c(SPC)S} \geq (PS + 1)t_{c(I)CLK} \geq 100$  ns, where PS is the prescale value set in the SPInCTL1[12:5] register bits.  
 For PS values of 0:  $t_{c(SPC)S} = 2t_{c(I)CLK} \geq 100$  ns.
- (6) The active edge of the SPInCLK signal referenced is controlled by the CLOCK POLARITY bit (SPInCTRL2.1).

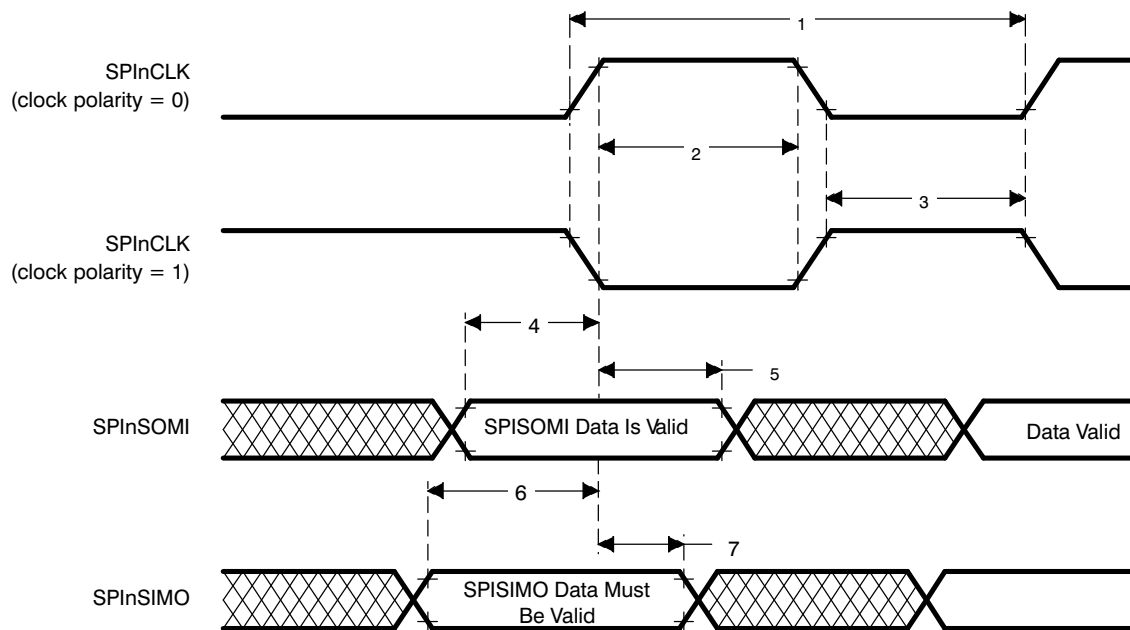


Figure 15. SPIn Slave Mode External Timing (CLOCK PHASE = 1)

## SCIn ISOSYNCHRONOUS MODE TIMINGS INTERNAL CLOCK

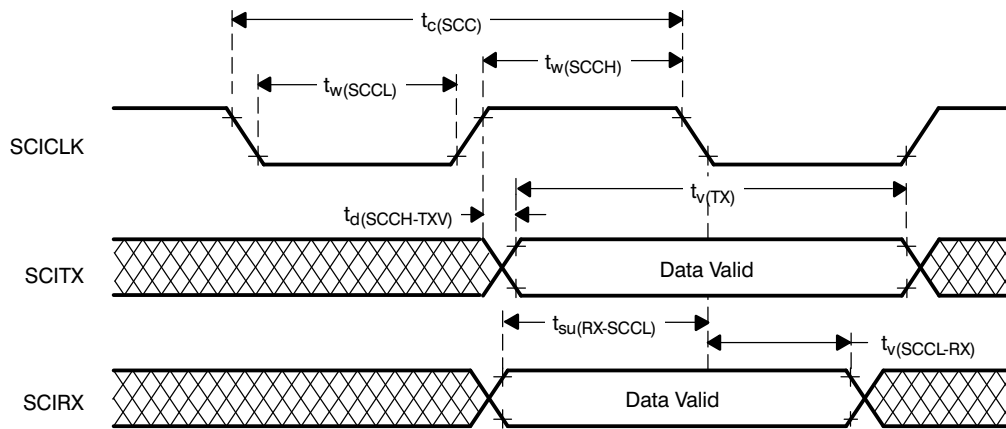
### Timing Requirements for Internal Clock SCIn Isosynchronous Mode<sup>(1)(2)(3)</sup>

		(BAUD + 1) IS EVEN OR BAUD = 0		(BAUD + 1) IS ODD AND BAUD ≠ 0		UNIT
		MIN	MAX	MIN	MAX	
$t_{c(SCC)}$	Cycle time, SCInCLK	$2t_{c(ICKL)}$	$2^{24}t_{c(ICKL)}$	$3t_{c(ICKL)}$	$(2^{24} - 1)t_{c(ICKL)}$	ns
$t_w(SCCL)$	Pulse duration, SCInCLK low	$0.5t_{c(SCC)} - t_f$	$0.5t_{c(SCC)} + 5$	$0.5t_{c(SCC)} + 0.5t_{c(ICKL)} - t_f$	$0.5t_{c(SCC)} + 0.5t_{c(ICKL)}$	ns
$t_w(SCCH)$	Pulse duration, SCInCLK high	$0.5t_{c(SCC)} - t_r$	$0.5t_{c(SCC)} + 5$	$0.5t_{c(SCC)} - 0.5t_{c(ICKL)} - t_r$	$0.5t_{c(SCC)} - 0.5t_{c(ICKL)}$	ns
$t_d(SCCH-TXV)$	Delay time, SCInCLK high to SCInTX valid		10		10	ns
$t_v(TX)$	Valid time, SCInTX data after SCInCLK low	$t_{c(SCC)} - 10$		$t_{c(SCC)} - 10$		ns
$t_{su}(RX-SCCL)$	Setup time, SCInRX before SCInCLK low	$t_{c(ICKL)} + t_f + 20$		$t_{c(ICKL)} + t_f + 20$		ns
$t_v(SCCL-RX)$	Valid time, SCInRX data after SCInCLK low	$-t_{c(ICKL)} + t_f + 20$		$-t_{c(ICKL)} + t_f + 20$		ns

(1) BAUD = 24-bit concatenated value formed by the SCI[H,M,L]BAUD registers.

(2)  $t_{c(ICKL)}$  = interface clock cycle time =  $1/f_{(ICKL)}$

(3) For rise and fall timings, see the "Switching Characteristics for Output Timings versus Load Capacitance" table.



- A. Data transmission/reception characteristics for isosynchronous mode with internal clocking are similar to the asynchronous mode. Data transmission occurs on the SCICLK rising edge, and data reception occurs on the SCICLK falling edge.

**Figure 16. SCIn Isosynchronous Mode Timing Diagram for Internal Clock**

## SCIn ISOSYNCHRONOUS MODE TIMINGS EXTERNAL CLOCK

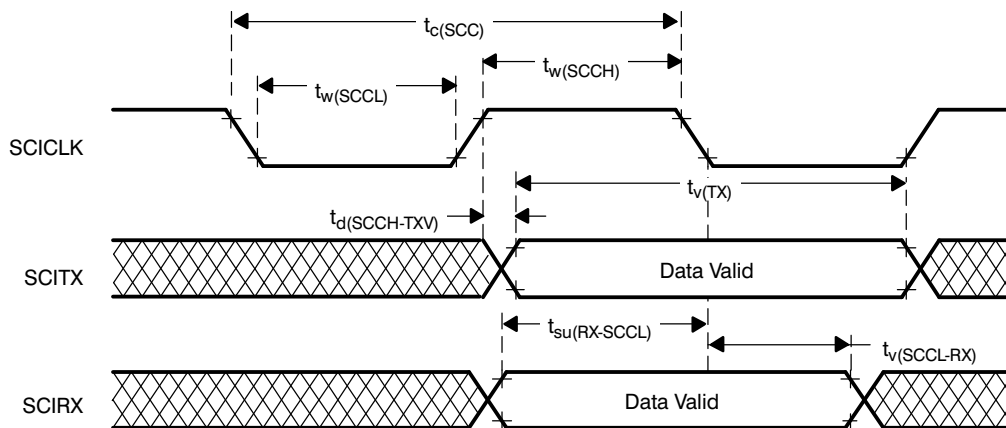
### Timing Requirements for External Clock SCIn Isosynchronous Mode<sup>(1)(2)</sup>

		MIN	MAX	UNIT
$t_{c(SCC)}$	Cycle time, SCInCLK <sup>(3)</sup>	$8t_{c(ICKL)}$		ns
$t_{w(SCCH)}$	Pulse duration, SCInCLK high	$0.5t_{c(SCC)} - 0.25t_{c(ICKL)}$	$0.5t_{c(SCC)} + 0.25t_{c(ICKL)}$	ns
$t_{w(SCCL)}$	Pulse duration, SCInCLK low	$0.5t_{c(SCC)} - 0.25t_{c(ICKL)}$	$0.5t_{c(SCC)} + 0.25t_{c(ICKL)}$	ns
$t_{d(SCCH-TXV)}$	Delay time, SCInCLK high to SCInTX valid	$2t_{c(ICKL)} + 12 + t_r$		ns
$t_{v(TX)}$	Valid time, SCInTX data after SCInCLK low	$2t_{c(SCC)} - 10$		ns
$t_{su(RX-SCCL)}$	Setup time, SCInRX before SCInCLK low	0		ns
$t_{v(SCCL-RX)}$	Valid time, SCInRX data after SCInCLK low	$2t_{c(ICKL)} + 10$		ns

(1)  $t_{c(ICKL)}$  = interface clock cycle time =  $1/f_{(ICKL)}$

(2) For rise and fall timings, see the "Switching Characteristics for Output Timings versus Load Capacitance" table.

(3) When driving an external SCInCLK, the following must be true:  $t_{c(SCC)} \geq 8t_{c(ICKL)}$



- A. Data transmission / reception characteristics for isosynchronous mode with external clocking are similar to the asynchronous mode. Data transmission occurs on the SCICLK rising edge, and data reception occurs on the SCICLK falling edge.

**Figure 17. SCIn Isosynchronous Mode Timing Diagram for External Clock**

## HIGH-END TIMER (HET) TIMINGS

### Minimum PWM Output Pulse Width:

This is equal to one high resolution clock period (HRP). The HRP is defined by the 6-bit high resolution prescale factor (hr), which is user defined, giving prescale factors of 1 to 64, with a linear increment of codes.

Therefore, the minimum PWM output pulse width =  $HRP(\min) = hr(\min)/SYSCLK = 1/SYSCLK$

For example, for a SYSCLK of 30 MHz, the minimum PWM output pulse width =  $1/30 = 33.33\text{ns}$

### Minimum Input Pulses that Can Be Captured:

The input pulse width must be greater or equal to the low resolution clock period (LRP), i.e., the HET loop (the HET program must fit within the LRP). The LRP is defined by the 3-bit loop-resolution prescale factor (lr), which is user defined, with a power of 2 increment of codes. That is, the value of lr can be 1, 2, 4, 8, 16, or 32.

Therefore, the minimum input pulse width =  $LRP(\min) = hr(\min) * lr(\min)/SYSCLK = 1 * 1/SYSCLK$

For example, with a SYSCLK of 30 MHz, the minimum input pulse width =  $1 * 1/30 = 33.33 \text{ ns}$

#### NOTE:

Once the input pulse width is greater than LRP, the resolution of the measurement is still HRP. (That is, the captured value gives the number of HRP clocks inside the pulse.)

Abbreviations:

hr = HET high resolution divide rate = 1, 2, 3,...63, 64

lr = HET low resolution divide rate = 1, 2, 4, 8, 16, 32

High resolution clock period =  $HRP = hr/SYSCLK$

Loop resolution clock period =  $LRP = hr*lr/SYSCLK$

## STANDARD CAN CONTROLLER (SCC) MODE TIMINGS

### Dynamic Characteristics for the CANSTX and CANSRX Pins

PARAMETER		MIN	MAX	UNIT
$t_d(\text{CANSTX})$	Delay time, transmit shift register to CANSTX pin <sup>(1)</sup>		15	ns
$t_d(\text{CANSRX})$	Delay time, CANSRX pin to receive shift register		5	ns

(1) These values do not include the rise/fall times of the output buffer.

## MULTI-BUFFERED A-TO-D CONVERTER (MibADC)

The multi-buffered A-to-D converter (MibADC) has a separate power bus for its analog circuitry that enhances the A-to-D performance by preventing digital switching noise on the logic circuitry which could be present on  $V_{SS}$  and  $V_{CC}$  from coupling into the A-to-D analog stage. All A-to-D specifications are given with respect to  $AD_{REFLO}$  unless otherwise noted.

Resolution	10 bits (1024 values)
Monotonic	Assured
Output conversion code	00h to 3FFh [00 for $V_{AI} \leq AD_{REFLO}$ ; 3FF for $V_{AI} \geq AD_{REFHI}$ ]

### MibADC Recommended Operating Conditions<sup>(1)</sup>

		MIN	MAX	UNIT
$AD_{REFHI}$	A-to-D high -voltage reference source	$V_{SSAD}$	$V_{CCAD}$	V
$AD_{REFLO}$	A-to-D low-voltage reference source	$V_{SSAD}$	$V_{CCAD}$	V
$V_{AI}$	Analog input voltage	$V_{SSAD} - 0.3$	$V_{CCAD} + 0.3$	V
$I_{AIC}$	Analog input clamp current <sup>(2)</sup> ( $V_{AI} < V_{SSAD} - 0.3$ or $V_{AI} > V_{CCAD} + 0.3$ )	-2	2	mA

(1) For  $V_{CCAD}$  and  $V_{SSAD}$  recommended operating conditions, see the "Device Recommended Operating Conditions" table.

(2) Input currents into any ADC input channel outside the specified limits could affect conversion results of other channels.

### Operating Characteristics over Full Ranges of Recommended Operating Conditions<sup>(1)(2)</sup>

PARAMETER		DESCRIPTION/CONDITIONS	MIN	TYP	MAX	UNIT
$R_i$	Analog input resistance	See <a href="#">Figure 18</a> .		250	500	$\Omega$
$C_i$	Analog input capacitance	Conversion			10	pF
		Sampling			30	pF
$I_{AIL}$	Analog input leakage current	See <a href="#">Figure 18</a> .	-1		1	$\mu$ A
$I_{ADREFHI}$	$AD_{REFHI}$ input current	$AD_{REFHI} = 3.6$ V, $AD_{REFLO} = V_{SSAD}$			5	mA
CR	Conversion range over which specified accuracy is maintained	$AD_{REFHI} - AD_{REFLO}$	3		3.6	V
$E_{DNL}$	Differential nonlinearity error	Difference between the actual step width and the ideal value after offset correction. See <a href="#">Figure 19</a> .			$\pm 2$	LSB
$E_{INL}$	Integral nonlinearity error	Maximum deviation from the best straight line through the MibADC. MibADC transfer characteristics, excluding the quantization error after offset correction. See <a href="#">Figure 20</a> .			$\pm 2$	LSB
$E_{TOT}$	Total error/Absolute accuracy	Maximum value of the difference between an analog value and the ideal midstep value. See <a href="#">Figure 21</a> .			$\pm 2$	LSB

(1)  $V_{CCIO} = V_{CCAD} = AD_{REFHI}$

(2)  $1 \text{ LSB} = (AD_{REFHI} - AD_{REFLO})/2^{10}$  for the MibADC

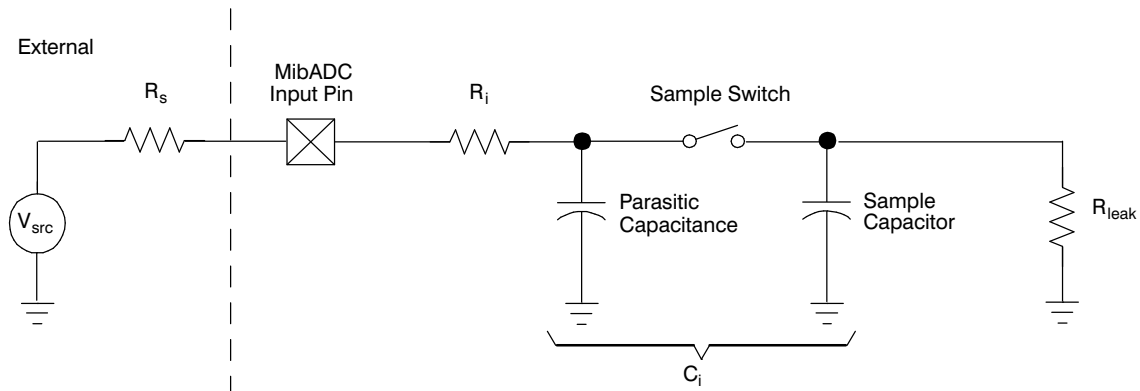


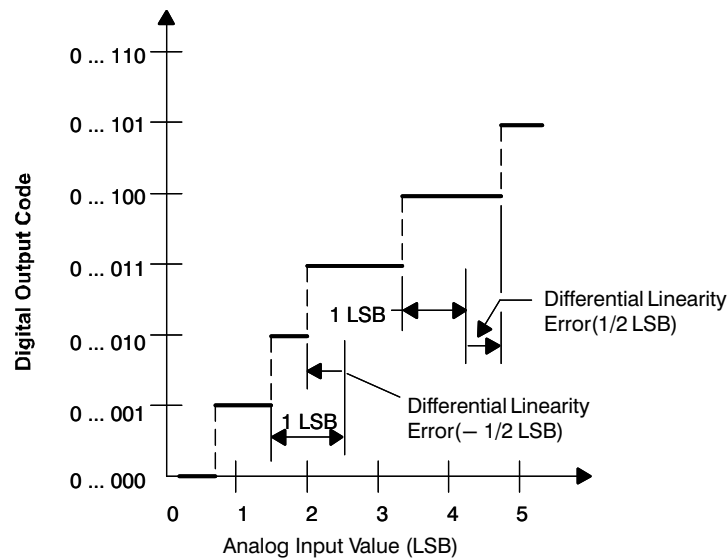
Figure 18. MibADC Input Equivalent Circuit

### Multi-Buffer ADC (MibADC) Timing Requirements

		MIN	MAX	UNIT
$t_{c(ADCLK)}$	Cycle time, MibADC clock	0.05		$\mu\text{s}$
$t_{d(SH)}$	Delay time, sample and hold time	1		$\mu\text{s}$
$t_{d(C)}$	Delay time, conversion time	0.55		$\mu\text{s}$
$t_{d(SHC)}^{(1)}$	Delay time, total sample/hold and conversion time	1.55		$\mu\text{s}$

(1) This is the minimum sample/hold and conversion time that can be achieved. These parameters are dependent on many factors; for more details, see the *TMS470R1x Multi-Buffered Analog-to-Digital Converter (MibADC) Reference Guide* (literature number SPNU206).

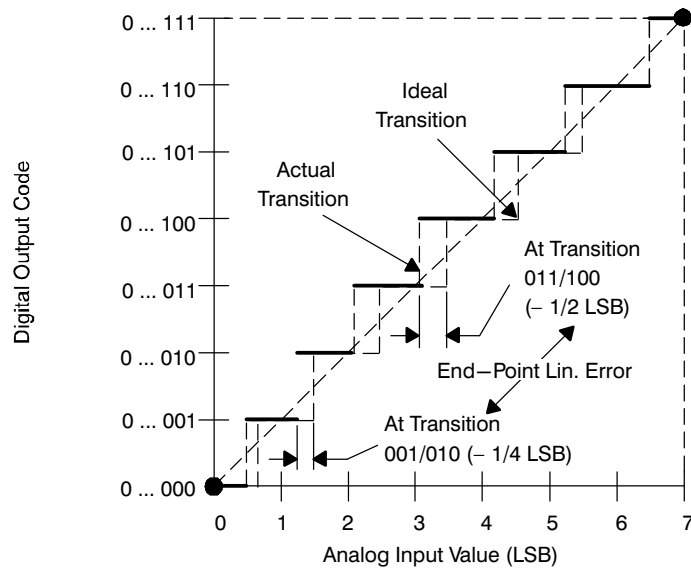
The differential nonlinearity error shown in Figure 19 (sometimes referred to as differential linearity) is the difference between an actual step width and the ideal value of 1 LSB.



$$A. \quad 1 \text{ LSB} = (AD_{REFHI} - AD_{REFLO})/2^{10}$$

Figure 19. Differential Nonlinearity (DNL)

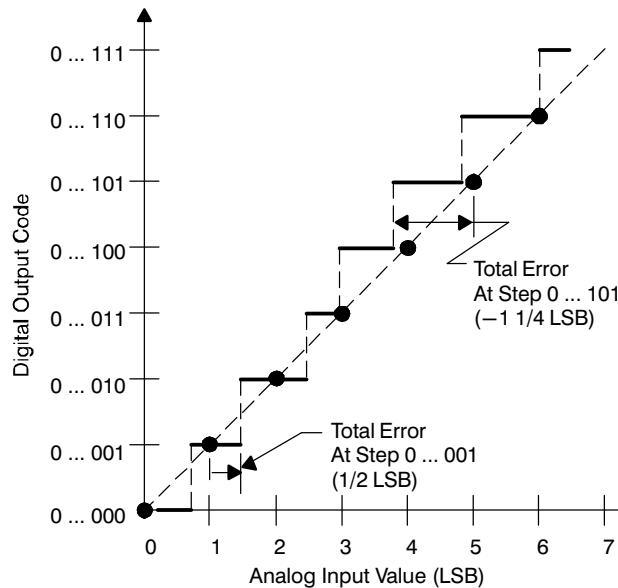
The integral nonlinearity error shown in Figure 20 (sometimes referred to as linearity error) is the deviation of the values on the actual transfer function from a straight line.



A.  $1 \text{ LSB} = (AD_{\text{REFHI}} - AD_{\text{REFLO}})/2^{10}$

**Figure 20. Integral Nonlinearity (INL) Error**

The absolute accuracy or total error of an MibADC as shown in Figure 21 is the maximum value of the difference between an analog value and the ideal midstep value.



A.  $1 \text{ LSB} = (AD_{\text{REFHI}} - AD_{\text{REFLO}})/2^{10}$

**Figure 21. Absolute Accuracy (Total) Error**

**TMS470R1A128**  
**16/32-Bit RISC Flash Microcontroller**

SPNS098A–JULY 2005–REVISED SEPTEMBER 2005

---

**THERMAL RESISTANCE CHARACTERISTICS**

PARAMETER	°C/W
$R_{\theta JA}$	51
$R_{\theta JC}$	5

## Revision History

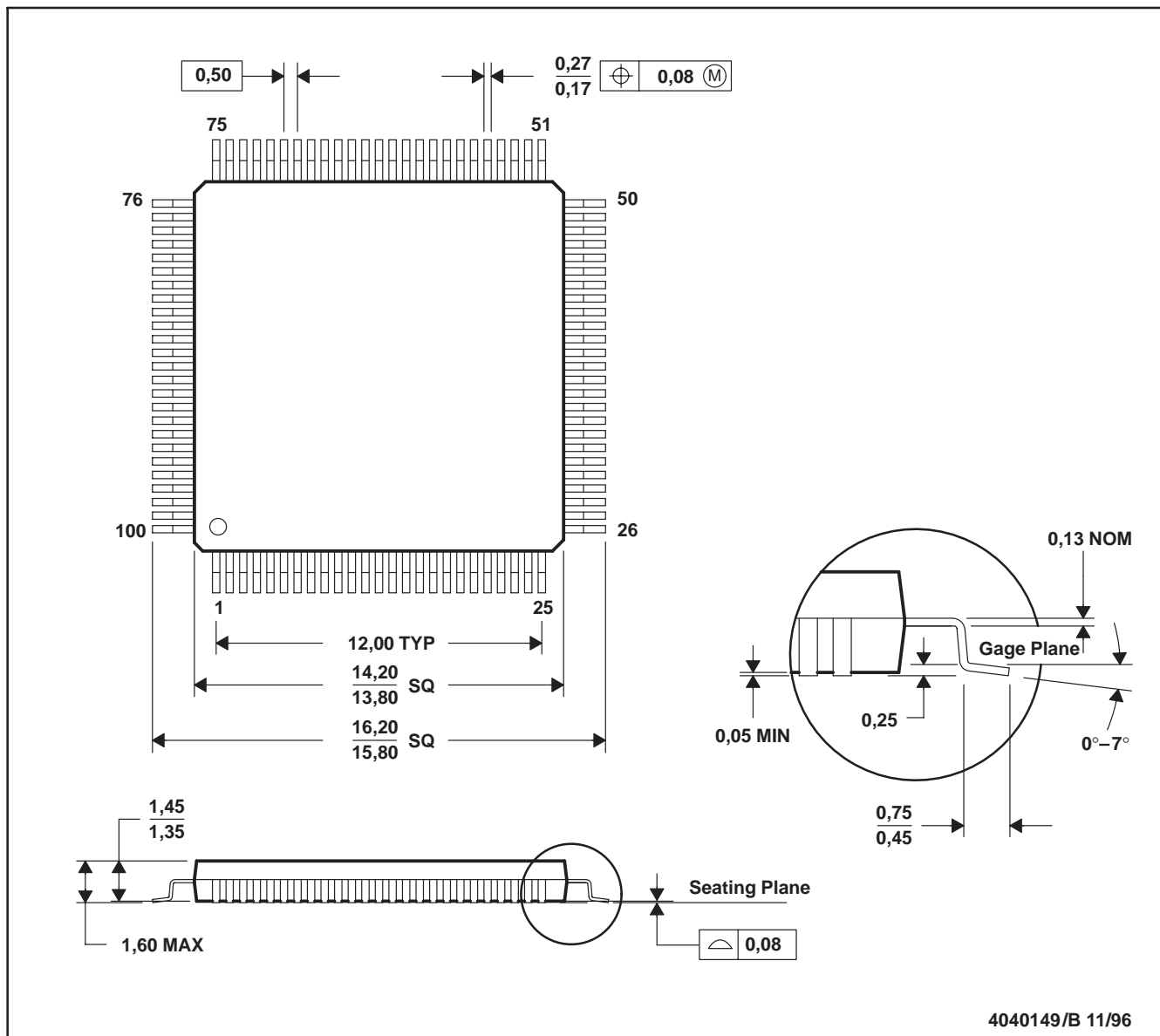
This revision history highlights the changes made to the device-specific datasheet SPNS098 to create the SPNS098A version.

**Table 9. Revision History**

Moved "XOR Share" section to "Description" section.
Changed the Family Nomenclature drawing, <a href="#">Figure 2</a> , to reflect T version of the temperature range.
Revised "Absolute Maximum Ratings" table to show T version of the temperature range.
Revised "Device Recommended Operating Conditions" table to show T version of the temperature range.
Added "Device and Development-Support Tool Nomenclature" information.
Changed VCC to 2.06 V in the ICC in the "Electrical Characteristics over Recommended Operating Free-Air Temperature Range" table.
Moved 2.75 from Max to Min column for $V_{CCIOPORH}$ in "Timing Requirements for $\overline{PORRST}$ " table.
Added row for $T_{ISU}$ to "Switching Characteristics over Recommended Operating Conditions for $\overline{RST}$ " table.
Added rows for $T_{fp(RST)}$ , $T_{fp(SLEEP)}$ , and $T_{fp(STANDBY)}$ to "Flash Timings" table.

PZ (S-PQFP-G100)

PLASTIC QUAD FLATPACK



- NOTES: A. All linear dimensions are in millimeters.  
 B. This drawing is subject to change without notice.  
 C. Falls within JEDEC MS-026

## IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

<b>Products</b>		<b>Applications</b>	
Amplifiers	<a href="http://amplifier.ti.com">amplifier.ti.com</a>	Audio	<a href="http://www.ti.com/audio">www.ti.com/audio</a>
Data Converters	<a href="http://dataconverter.ti.com">dataconverter.ti.com</a>	Automotive	<a href="http://www.ti.com/automotive">www.ti.com/automotive</a>
DSP	<a href="http://dsp.ti.com">dsp.ti.com</a>	Broadband	<a href="http://www.ti.com/broadband">www.ti.com/broadband</a>
Interface	<a href="http://interface.ti.com">interface.ti.com</a>	Digital Control	<a href="http://www.ti.com/digitalcontrol">www.ti.com/digitalcontrol</a>
Logic	<a href="http://logic.ti.com">logic.ti.com</a>	Military	<a href="http://www.ti.com/military">www.ti.com/military</a>
Power Mgmt	<a href="http://power.ti.com">power.ti.com</a>	Optical Networking	<a href="http://www.ti.com/opticalnetwork">www.ti.com/opticalnetwork</a>
Microcontrollers	<a href="http://microcontroller.ti.com">microcontroller.ti.com</a>	Security	<a href="http://www.ti.com/security">www.ti.com/security</a>
		Telephony	<a href="http://www.ti.com/telephony">www.ti.com/telephony</a>
		Video & Imaging	<a href="http://www.ti.com/video">www.ti.com/video</a>
		Wireless	<a href="http://www.ti.com/wireless">www.ti.com/wireless</a>

Mailing Address: Texas Instruments  
Post Office Box 655303 Dallas, Texas 75265